

# AMAZONE

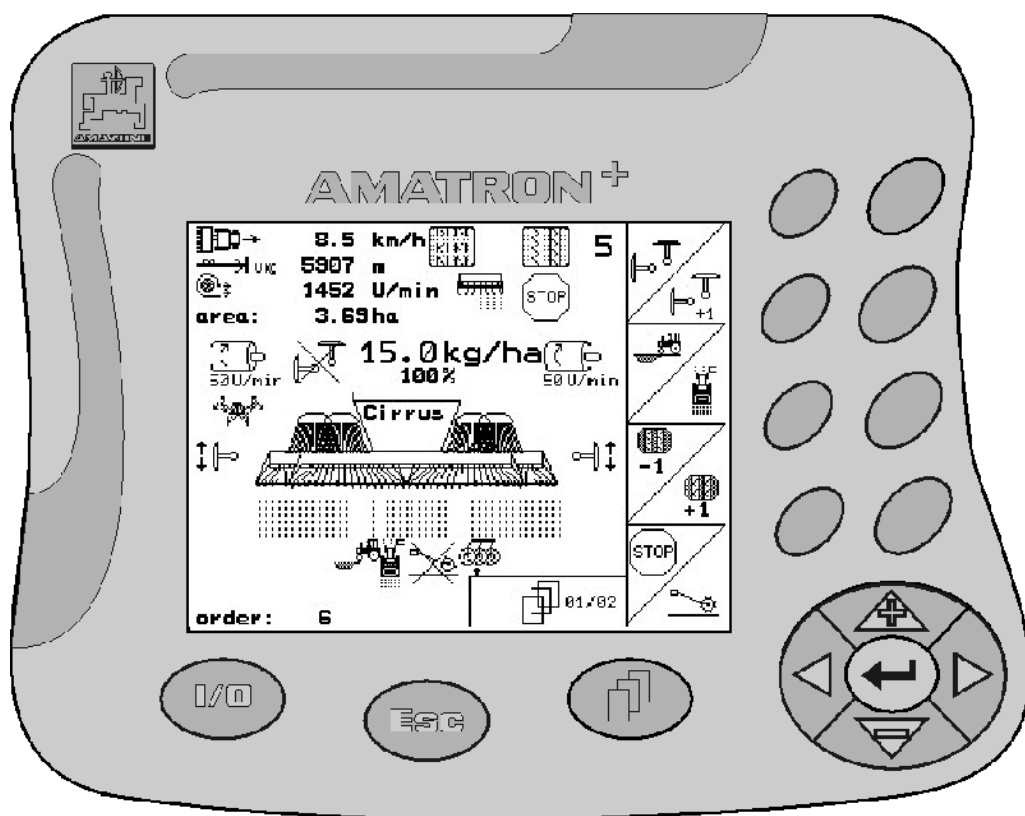
## Operator's Manual

On-board computer

**AMATRON<sup>+</sup>**

for use in conjunction with

**Cirrus** and **Citan**



MG 927  
DB2031-4 GB 03.06  
Printed in Germany



Before starting to operate,  
please carefully read and  
adhere to this instruction  
manual and safety advice.



## Preface

Dear customer,

The **AMATRON<sup>+</sup>** on-board computer is yet another quality product from the comprehensive range of farm equipment manufactured by AMAZONEN-WERKE, H. Dreyer GmbH & Co. KG.

In order to ensure you make the fullest use of your on-board computer in conjunction with **Cirrus** Packer coulter sowing combinations we recommend that you carefully read and observe the information within this instruction manual and adhere to the advice given therein.

Please ensure that this instruction manual is made available to any operator before he or she starts to operate the machine.

This instruction manual refers to the **AMATRON<sup>+</sup>** on-board computer when used in conjunction with **Cirrus**.



**Amazonen-Werke**

H.Dreyer GmbH & Co. KG

## Contents

<b>1.</b>	<b>Details about the computer and its range of application.....</b>	<b>5</b>
1.1	Manufacturer .....	5
1.2	Conformity declaration .....	5
1.3	Details required when making enquiries and ordering.....	5
1.4	Intended use of the on-board computer .....	5
1.5	Identification .....	5
<b>2.</b>	<b>Safety .....</b>	<b>6</b>
2.1	Dangers when not adhering to this safety advice .....	6
2.2	Qualification of operator .....	6
2.3	Symbols in this instruction manual.....	6
2.3.1	General danger symbol .....	6
2.3.2	Attention symbol .....	6
2.3.3	Advice symbol .....	6
2.4	Safety advice for retrofitting electric and electronic devices and/or components .....	7
2.5	Safety advice for repair work.....	7
<b>3.</b>	<b>Fitting instruction.....</b>	<b>8</b>
3.1	Mounting of the terminal.....	8
3.2	Connecting the terminal .....	9
3.3	Battery connecting cable.....	10
<b>4.</b>	<b>Description of product .....</b>	<b>11</b>
4.1	Description of keys .....	12
4.2	Shift – key.....	14
1.1	14 .....	
4.3	Hierarchy of <b>AMATRON<sup>+</sup></b> .....	15
4.4	Input of information into <b>AMATRON<sup>+</sup></b> .....	16
4.5	Input of text and figures.....	16
4.5.1	Selection of options .....	17
4.5.2	Toggle Function.....	17
<b>5.</b>	<b>Operation .....</b>	<b>18</b>
5.1	Start screen .....	18
5.2	Main menu.....	18
5.2.1	Input of machine data .....	19
5.2.1.1	Input of the sown and unsown distances (m) for the intermittent tramline .....	22
5.2.1.2	Calibration of forward speed sensor .....	23
5.2.2	Creating a job .....	25
5.2.3	External job.....	26
5.2.4	Calibration .....	26
5.2.4.1	Calibration of the drill with remote seed rate control .....	27
5.2.4.2	Calibration of the drill with full electric metering system.....	29
5.2.5	Setup .....	31
5.2.6	Terminal Setup .....	35
<b>6.</b>	<b>Operation in the field .....</b>	<b>37</b>
6.1	<b>Cirrus</b> with Vario gearbox .....	38
6.1.1	Display – operational menu <b>Cirrus</b> with Vario gearbox .....	38
6.1.2	Advice on field operation .....	39
6.1.3	Key layout: Operational menu <b>Cirrus</b> with Vario gearbox .....	40
6.1.4	Layout menu - joystick.....	42
6.2	<b>Cirrus</b> with full electric metering system .....	43
6.2.1	Display – operational menu <b>Cirrus</b> with full electric metering system .....	43
6.2.2	Key description: Operational menu <b>Cirrus</b> with full electric metering system .....	45
6.2.3	Layout menu - joystick.....	47



6.3	<b>Citan</b> with Vario gearbox .....	48
6.3.1	Display – operational menu <b>Citan</b> with Vario gearbox .....	48
6.3.2	Advice on field operation .....	49
6.3.3	Key layout: Operational menu <b>Citan</b> with Vario gearbox.....	50
6.3.4	Layout menu - joystick.....	52
6.4	<b>Citan</b> with full electric metering system.....	53
6.4.1	Display – operational menu <b>Citan</b> with full electric metering system .....	53
6.4.2	Key description: Operational menu <b>Citan</b> with full electric metering system.....	55
6.4.3	Layout menu - joystick.....	57
7.	<b>Joystick</b> .....	58
7.1	Fitting .....	58
7.2	Function .....	58
7.3	Key layout.....	59
8.	<b>Maintenance</b> .....	60
8.1	Calibration of gearbox (not required for machines with full electric metering) .....	60
9.	<b>Help menu</b> .....	61
10.	<b>Malfunction</b> .....	62
10.1	Alarm .....	62
10.2	Failure of the forward speed sensor (Imp/100m) .....	63

## 1. Details about the computer and its range of application

The computer displays, controls and monitors the implement to which it is connected.

### 1.1 Manufacturer

#### AMAZONEN-WERKE

H. DREYER GmbH & Co. KG  
Am Amazonenwerk 9-13  
D-49205 Hasbergen-Gaste

### 1.2 Conformity declaration

The board computer fulfils the EMV-guide line 89/336/EC.

### 1.3 Details required when making enquiries and ordering

When ordering spare parts always state the serial number of the on-board computer.



**The safety requirements are only fulfilled when, in the event of repair, only original AMAZONE spare parts are used. The use of non-genuine parts may rule out any liability for resulting damage.**

### 1.5 Identification

Type plate on the on board computer.



**The type plate is of documentary value and may not be changed or disguised.**

### 1.4 Intended use of the on-board computer

The computer has been exclusively designed for normal operation in agriculture as a display, monitoring and controlling system in combination with a wide range of **AMAZONE** equipment (in this instance: **Cirrus / Citan**).

Use for any other purpose than that stipulated above is no longer regarded as intended use. The manufacturer does not accept any responsibility for damage resulting from this and therefore, the operator himself carries the full risk.

Under "intended use" the operator must adhere to the manufacturer's prescribed operation, maintenance and repair conditions and **exclusively use original AMAZONE spare parts**.

The implement may only be operated, maintained and repaired by persons who are familiar with it and who have been informed about the possible dangers.

All applicable accident prevention advice as well as any further generally accepted safety, working, medical and road traffic rules and regulations should be adhered to.

Though our machines having been manufactured with the greatest of care deviations in use cannot totally be excluded even when used as intended. These deviations may be caused by, for example:

Blocking up or bridging (e.g. by foreign particles, bag residues, damp fertiliser, seed, spray chemicals etc.),

Normal wear and tear

- Damage by external influence,
- Wrong PTO input speed or travelling speeds,
- Wrong adjustment of the machine (incorrect mounting, not adhering to the operator's manual, setting chart).

Before and also during every operation check the proper function of the accuracy of application.

Claims for damage that has occurred anywhere but on the on-board computer itself will be rejected. This also applies to damage due to application errors when fertilising, seeding or spraying. Arbitrary modifications to the on-board computer may result in damage and therefore, the manufacturer does not accept liability for such damage.

Arbitrary changes on the implement may cause consequential damage and rule out the liability of the supplier/manufacturer for this damage.



## 2. Safety

This instruction manual contains basic advice that must be adhered to when mounting, operating and maintaining the machine. Ensure that this instruction manual has been read by the user/operator before starting to operate the device and that it is made really available at all times to the user.

Please strictly observe and adhere to all safety advice given in this instruction manual.

### 2.1 Dangers when not adhering to this safety advice

Not adhering to the safety advice given

- may result in endangering the user or other persons, the environment and/or the machine itself.
- may result in the loss of any claim for damage.

Not paying attention to the safety advice may cause the following risks:

- Danger to persons present within the operational range.
- Failure of important functions of the machine.
- Failure of prescribed measures for maintenance and repair.
- Danger to persons from mechanical or chemical affects.
- Danger to the environment from leaking hydraulic oil.

### 2.2 Qualification of operator

The implement may only be operated, maintained and repaired by persons, who are acquainted with it and have been informed of the relevant dangers.

### 2.3 Symbols in this instruction manual

#### 2.3.1 General danger symbol



Not adhering to the safety advice in this instruction manual may cause danger to health and life of persons. They are identified by the general danger symbol (Safety symbol according to DIN 4844-W9).

#### 2.3.2 Attention symbol



Safety advice, where damage may be caused to the machine and it's function when not being adhered to, are identified with the attention symbol.

#### 2.3.3 Advice symbol



Advice regarding the machine's specific particularities, which have to be adhered to for a faultless function of the machine are identified with the advice symbol.

## 2.4 Safety advice for retrofitting electric and electronic devices and/or components

The function of the implements' electronic components and parts may be affected by the electro-magnetic transmittance of other devices. Such affects may endanger people if the following safety advice has not been adhered to:

When retrofitting electric and electronic devices and/or components to the implement with a connection to the tractor's on-board electric circuit, the onus is on the user to ensure that the installation will not cause any disturbance to either the tractor's electronics or other components.

Special attention must be paid that the retrofitted electric and electronic parts correspond to the EMV-guideline 89/336/EC in the relevant valid edition and that they bear the CE-mark.

For retrofitting mobile communication systems (e.g. radio, telephone) the following requirements must be fulfilled:

Only install devices that have officially been authorised for the country of use.

Fix the device securely.

For cabling and installation as well as for the maximum permissible current supply, adhere to the fitting instructions of the implement manufacturer.

## 2.5 Safety advice for repair work



**Before carrying out any repair work on the electric system or arc welding on the tractor or the mounted implement, disconnect all connections to the on-board computer.**



### 3. Fitting instruction

#### 3.1 Mounting of the terminal

Fit the base tractor equipment (Fig. 1/1) (console and distributor) within reach and sight to the right hand side of the operator. It must be installed in the tractor cab free from vibration and disturbance from electrical conductivity. The distance from a radio transmitter or an antenna should at least be 1 m.



**Via the console the computer housing must have a conductive connection to the tractor chassis.**

**Before fitting, scratch off the paint around the contact area of the bracket to avoid an electrostatic charging..**

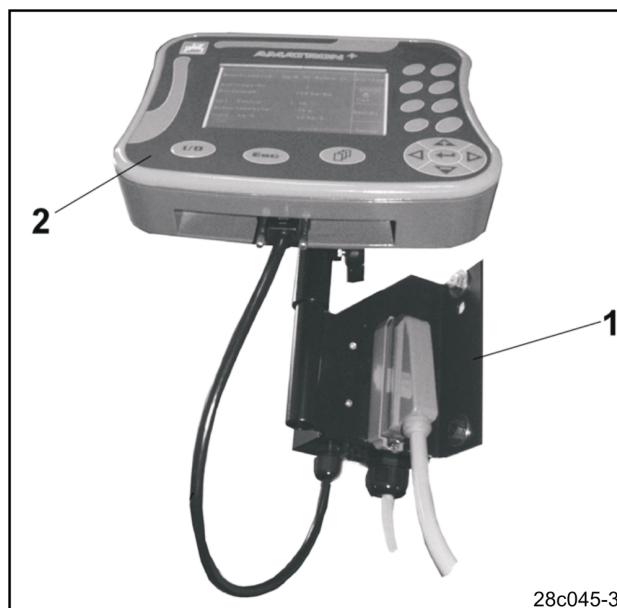


Fig. 1

The terminal is attached with a fixing bracket (Fig. 2/1) to the console and then locked tight with the thumb bolt (Fig. 2/2) .



Fig. 2



## 3.2 Connecting the terminal

The terminal (Fig. 3/2) is designed for use in conjunction with all AMAZONE machines via the **AMATRON<sup>+</sup>** job computer.

Connect the terminal (Fig. 3/2) to the console (Fig. 3/1) as follows:

- connect the seed drill to the base tractor equipment via the machine plug (Fig. 3/3)
- Connect the battery cable (Fig. 3/4) with the tractor battery. For advice regarding power supply, please refer to para. 3.3.
- Connect the intermediate cable (Fig. 3/5) with the terminal (Fig. 3/2).

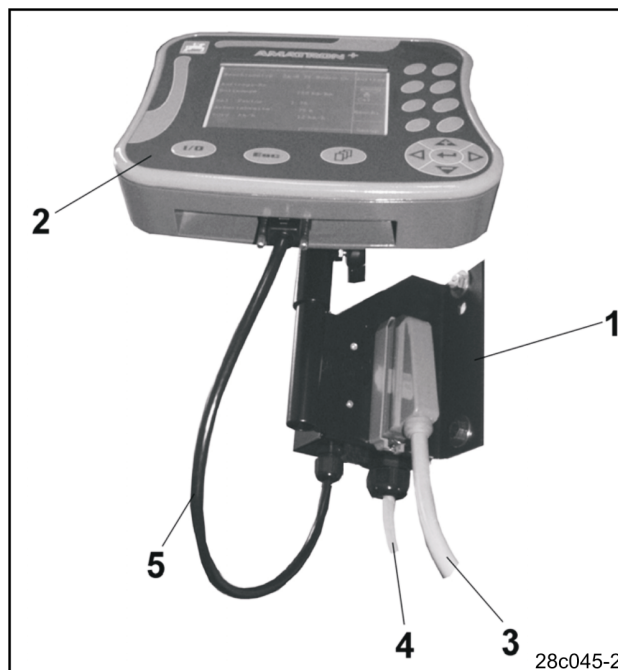


Fig. 3

- Insert the plug of the intermediate cable (Fig. 3/6) into the central 9-pin Sub-D socket (Fig. 4/1).
- The serial interface socket (Fig. 4/2 ) allows an additional connection to a GPS-Terminal.

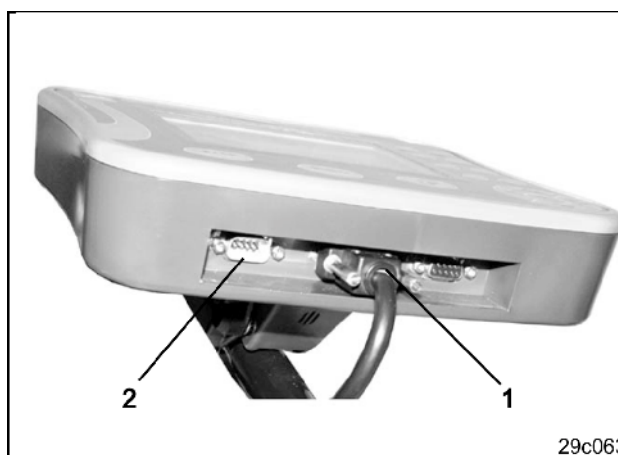


Fig. 4



### 3.3 Battery connecting cable

The required power supply of **12 V** should be provided directly from the battery.



**Before connecting **AMATRON<sup>+</sup>** with a tractor that is equipped with several batteries, please refer to either the tractor's manual to ascertain the battery to which the computer should be connected, or ask the tractor manufacturer.**

- Route the battery connecting cable from the tractor cab to the tractor battery and secure. Ensure that the battery connecting cable cannot be trapped.
- Shorten the battery connecting cable as necessary.
- Strip the cable end by approx. 250 to 300 mm.
- Individually remove the insulation from the cable ends by 5 mm.
- Insert the blue cable (earth cable) into the loose ring tongue (Fig. 6/1).
- Use crimping pliers to secure the joint.
- Insert the brown cable (+ 12 Volt) into the free butt joint (Fig. 6/2).
- Use crimping pliers to secure the joint.
- Shrink the casing over the butt joint (Fig. 6/2) by using a heat source (lighter or hair dryer) until the adhesive escapes.

Connect battery cable to tractor battery:

- Brown cable with +.
- Blue cable with -.



**Before connecting **AMATRON<sup>+</sup>** with a tractor that is equipped with several batteries, please refer to either the tractor's manual to ascertain the battery to which the computer should be connected, or ask the tractor manufacturer.**

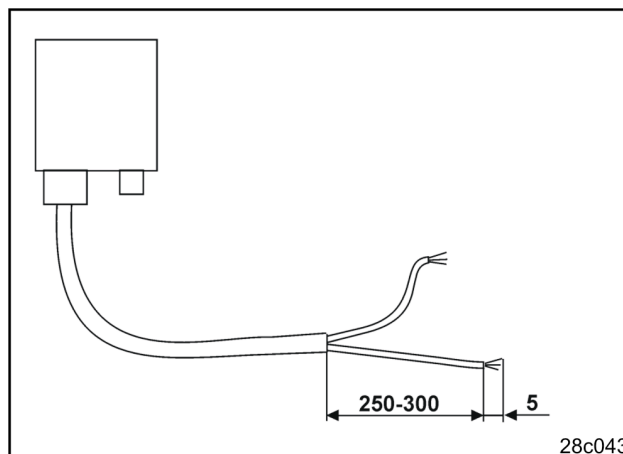


Fig. 5

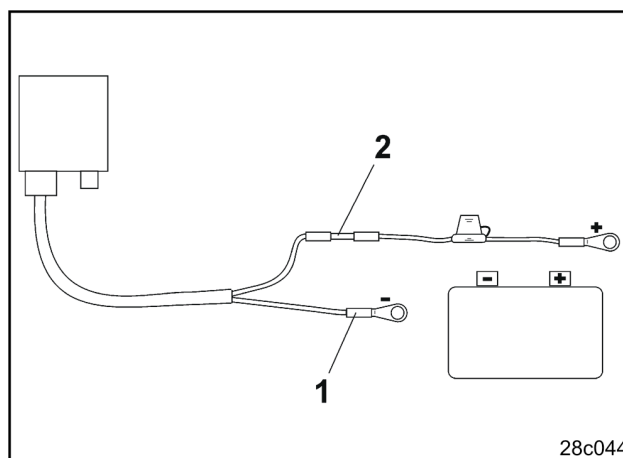


Fig. 6

#### 4. Description of product

**AMATRON<sup>+</sup>** can be used to control, actuate and monitor **AMAZONE** Packer Coulter sowing combinations

- **Cirrus**
- **Citan**

**AMATRON<sup>+</sup>** consists of the terminal (Fig. 7), the basic tractor equipment (fixed in the cab) and the job computer on the machine.

Any possible malfunction problems are automatically indicated visually and/or audibly.

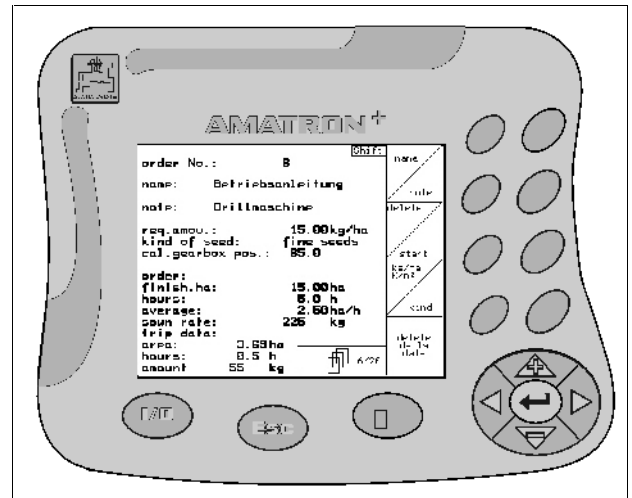


Fig. 7

This instruction manual refers from terminal-software version:

-Machine:	MHX-Version.:	2.14
-Terminal:	IOP-Ver.:	3.3.2
	BIN-Ver.:	3.14



## 4.1 Description of keys

The main screen functions are indicated on the right hand margin of the display by an icon (complete icon Fig. 8/1 or diagonally divided icon Fig. 8/2). These are accessed with the two rows of keys next to the right hand side of the display.

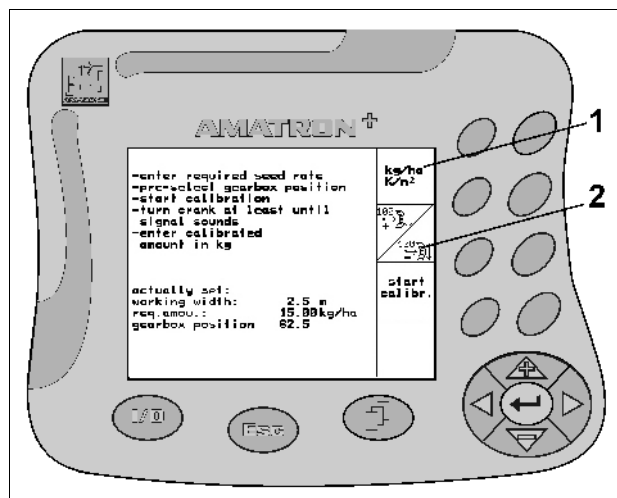




Fig. 8

When the fields are diagonally divided:

- the left hand key relates to the top left function icon (Fig. 9/1).
- the right hand key is related to the bottom right hand function icon (Fig. 9/2).

If a complete icon appears on the display only the right hand key relates to that function (Fig. 9/3).

- |  |  |
|--|--|
| <br> | <ul style="list-style-type: none"> <li>- On / Off ( travel on public roads only with the <b>AMATRON<sup>+</sup></b> switched off.).</li> <li>- Return to the previous screen.</li> <li>- Change from job menu ↔ main menu</li> <li>- Delete input</li> <li>- To return to the operational menu (keep key pressed for at least 1 second)</li> </ul> |
|--|--|

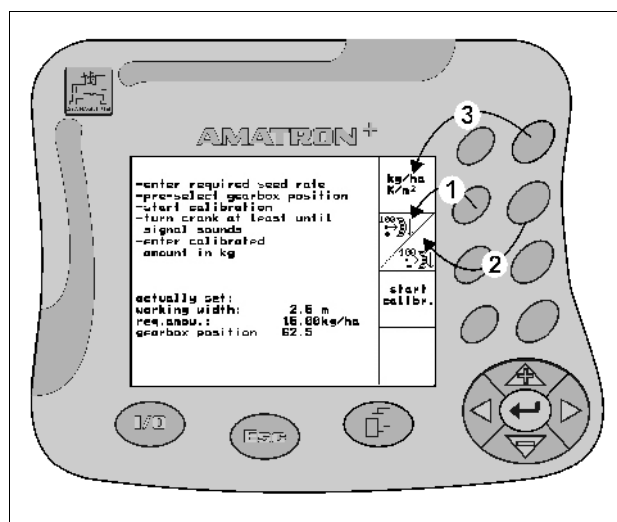


Fig. 9



- Page on to other menu pages (only possible when the page symbol (Fig. 10/1) appears in the display)
- Help menu only possible from the main menu.



- Cursor in the display to the right



- Cursor in the display to the left



- Accepting selected figures and letters
- Confirmation of a warning alarm
- Return to 100% application rate in the operational menu



- Cursor upwards in the display
- Increasing the sowing rate by the pre-set increment during operation (e.g.: +10%) (to set the quantity step please refer to para. 5.2.1)



- Cursor downwards in the display
- Reducing the sowing rate by the pre-set increment during operation (e.g.: -10%) (to set the quantity step please refer to para. 5.2.1).

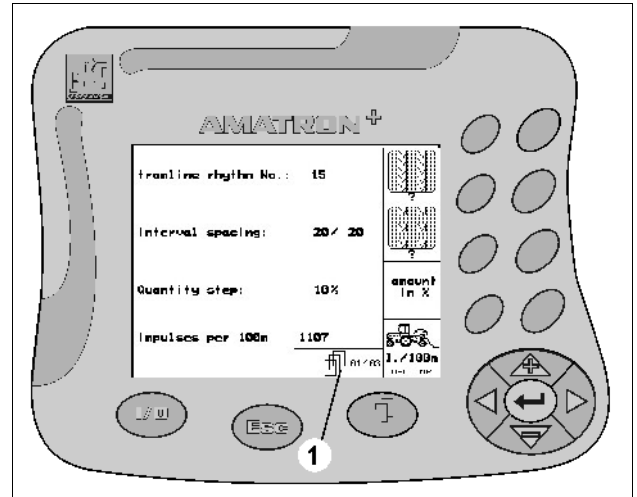


Fig. 10



## 4.2 Shift – key



The shift key is located on the rear of the terminal (Fig. 11/1).

### Active in the operation menu:

If the shift key (Fig. 11/1) on the rear of the terminal is pressed, the function icons additional function fields (Fig. 12) will appear in the operational menu and the coverage of the function keys will change accordingly (only possible, when shift (Fig. 13/1) appears on the display).

### Active in the job menu

If the shift key (Fig. 11/1) on the rear of the terminal

is pressed, the function icons  and  appear in the menu windows to page the jobs up and down.

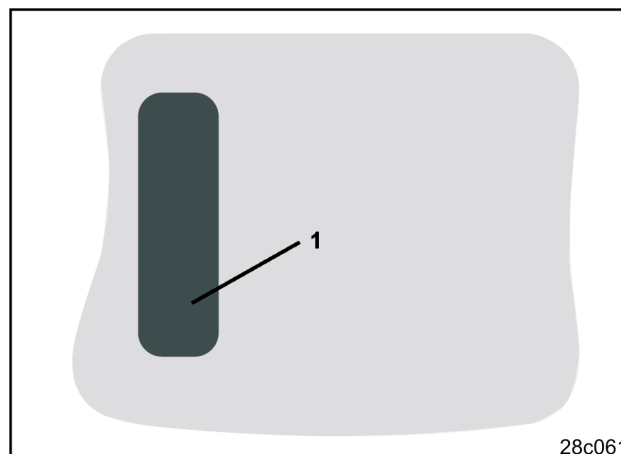


Fig. 11

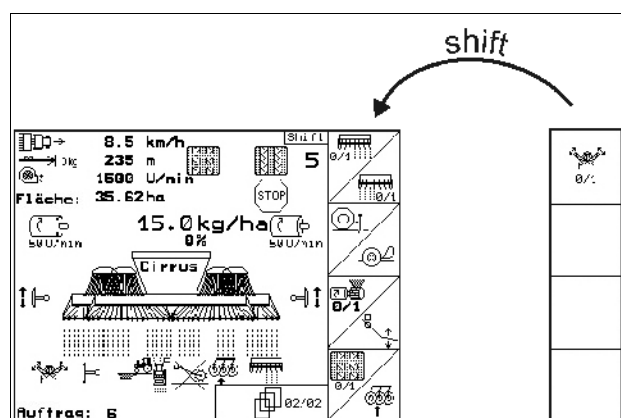


Fig. 12

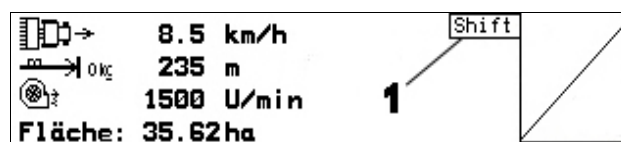
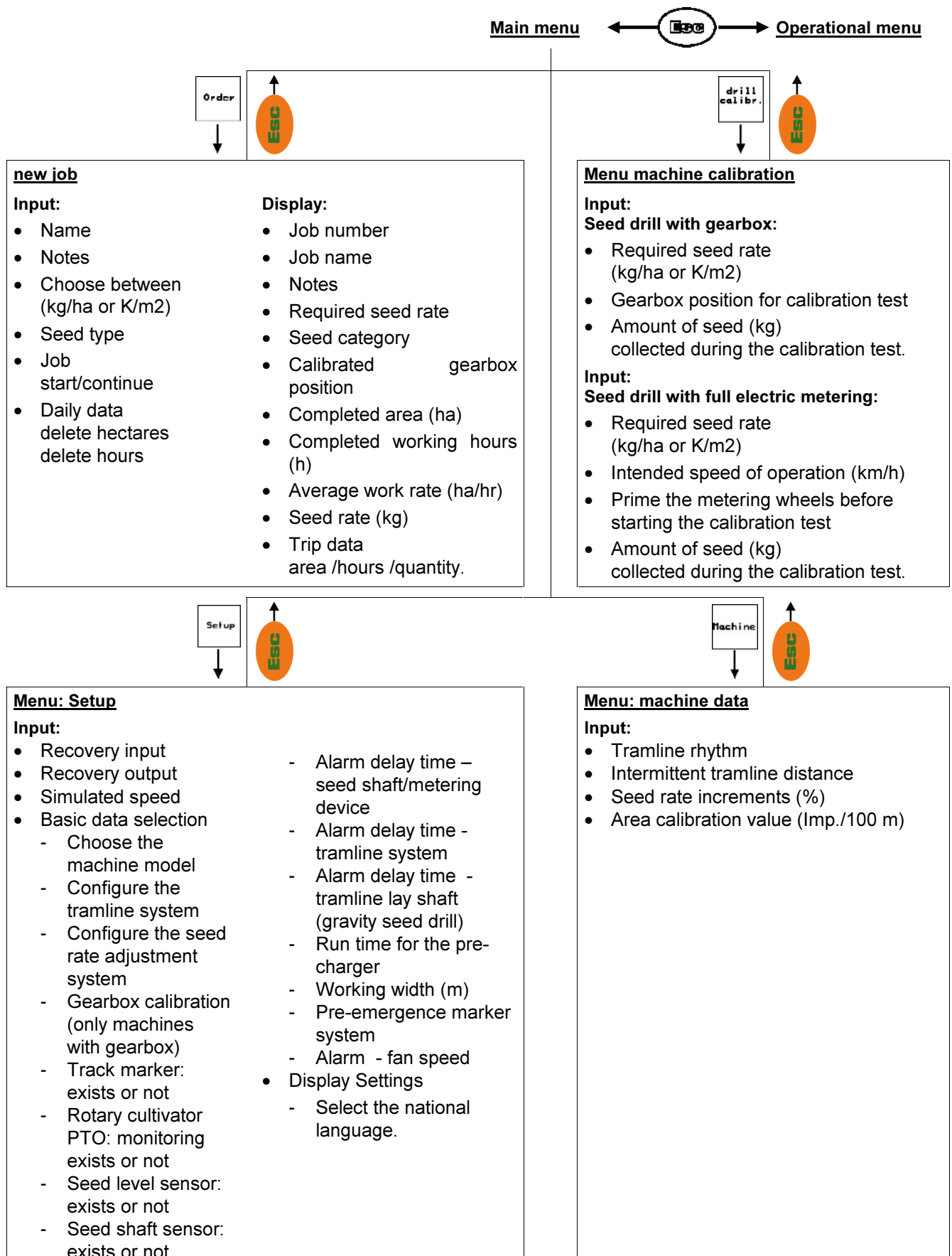


Fig. 13

### 4.3 Hierarchy of **AMATRON**<sup>+</sup>



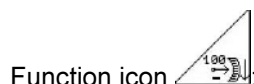


#### 4.4 Input of information into **AMATRON<sup>+</sup>**



To assist you in operating **AMATRON<sup>+</sup>** the function icons are illustrated in this instruction manual in order to make clear that the key related to that function icon should be pressed.

**Example:**



**Description in the operator's manual:**

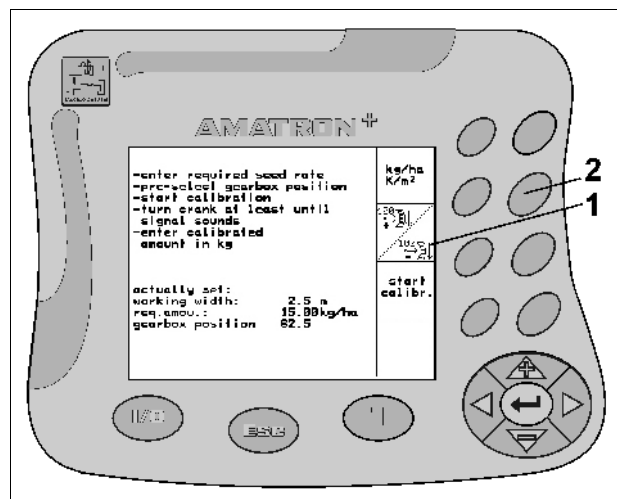


Reduces the gearbox lever setting to a lower position.

**Action:**

The operator actuates the key (Fig. 14/2) relating to

function icon (Fig. 14/1) to reduce the seed rate.



**Fig. 14**

#### 4.5 Input of text and figures

If **AMATRON<sup>+</sup>** requires the input of text or figures the entry menu (Fig. 15) appears.

The input block (Fig. 15/1) showing letters, figures and arrows, via which an entry (Fig. 15/2) (text or figure) can be made, appears in the lower half of the display.

- selecting letters or figures in the input field (Fig. 15/3).

- Accept the entry (Fig. 15/3).

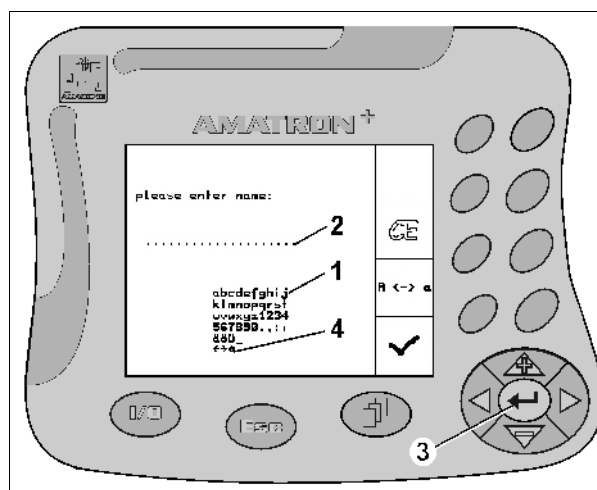
- Delete the last entry.

- Change the letter case

- Confirms input having finished the entry

The arrows (Fig. 15/4) allow the movement along the text line in the input block.




The arrow in the input block (Fig. 15/4) deletes the last entry.



**Fig. 15**



#### 4.5.1 Selection of options

- Position the cursor (Fig. 16/1) with  and .
-  Accept the entry (Fig. 16/2).

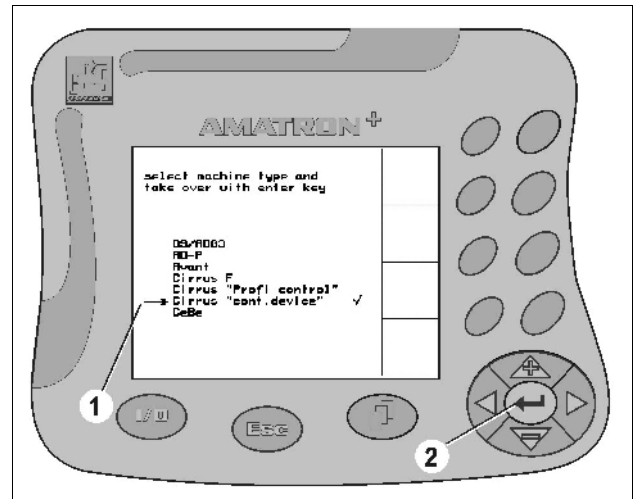


Fig. 16

#### 4.5.2 Toggle Function

On / off switching of functions, e.g. seed level sensor on / off.:

- Press function key (Fig. 16/2) once  
→ Function **On** (Fig. 16/1).
- Press function key once again  
→ Function **Off**.

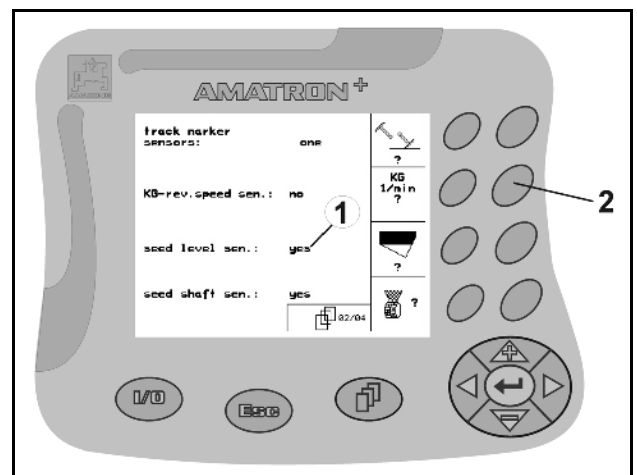


Fig. 17



## 5. Operation

### 5.1 Start screen

Having switched on the terminal, with the machine connected, the start menu will appear. It shows the terminal software version. After approx. 2 sec **AMATRON<sup>+</sup>** automatically jumps into the main menu.

After switching on the terminal **AMATRON<sup>+</sup>** may load data from the machine's job computer after, for example:

- installation of a new job computer,
- installation of a new **AMATRON<sup>+</sup>** terminal,
- a RESET of the **AMATRON<sup>+</sup>** terminal,

the start screen will show this message (Fig. 15).

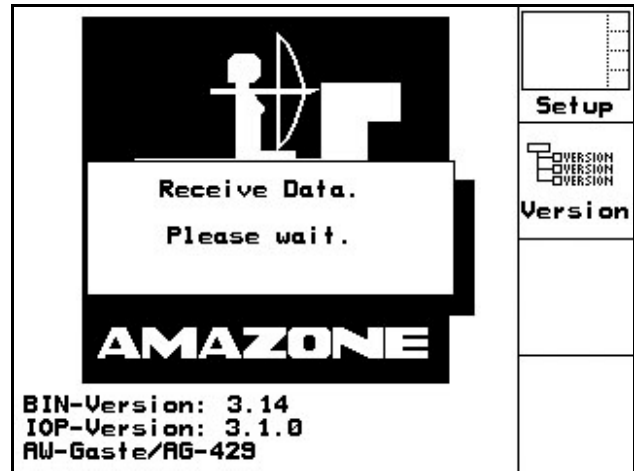


Fig. 18


### 5.2 Main menu







Order	Menu job: Input of data for a new job. Always start a job prior to drilling (see para 5.2.2).
drill calibr.	Menu calibration: always carry out a calibration test prior to any sowing operation (see para.5.2.3).
machine	Menu machine data: Input of machine specific or individual data (para 5.2.1).
Setup	Menu: Setup - input of data or information recall for service staff during maintenance or trouble-shooting (para. 5.2.5).

machine type:	Cirrus	Order
order No.:	6	drill calibr.
tramline rhythm No.:	15	machine
working width:	6.0m	Setup
working menu	aid	

Fig. 19

## 5.2.1 Input of machine data

Page one  menu: machine data (Fig. 20):

-  Inputting the required tramline rhythm (see tables Fig. 21 to Fig. 23).
-  Inputting the intermittent tramline function (see para. 5.2.1.1).
-  Inputting the application rate increase (as %) that the seed rate changes via the  &  during operation).
-  Calibration of hectare meter sensor (see para. 5.2.1.2).

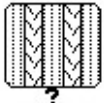


tramline rhythm No.:	15	
interval spacing:	20 / 20	
Quantity step:	10%	amount in %
impulses per 100m	1107	
		01/03

Fig. 20

Tramline rhythm	1	2	3	4	5	6	7	8	9	10	11	12	13	14
Tramline counter	0	0	0	0	0	0	0	0	0	1	1	0	0	0
	1	0	1	1	1	1	1	1	1	2	0	1	1	1
		1	2	2	2	2	2	2	2	3	3	2	2	2
		2		3	3	3	3	3	3	0	4	3	3	3
					4	4	4	4	4	5	5	4	4	4
						5	5	5	5	6	6	5	5	5
							6	6	6	0	7	6	6	6
								7	7	8	8	7	7	7
									8	9	0	8	8	8
										10	10	9	9	9
												10	10	10
													11	11
														12
														13

Fig. 21








Tramline rhythm	15	16	17	20	21	22	23	26	32					
Tramline counter	1	0	0	0	0	0	0	0	0					
	Rhythm 15 does not create any tramlines	1	1	1	0	0	0	1	0					
		2	2	2	1	1	1	2	1					
		3	3	3	2	2	2	3	2					
		4	4	4	3	3	3	4	3					
		5	5	5	4	4	4	5	4					
		6	6	6		5	5	6	5					
		7	7	7		6	6	7	6					
		8	8	8			7	8	7					
		9	9	9			8	9	8					
		10	10					10	9					
		11	11						10					
		12	12											
		13	13											
		14	14											
		15	15											
			16											

Fig. 22

Double tramline control																				
Tramline rhythm	18 left hand	18 right hand	19 left hand	19 right hand	24 left hand	24 right hand	25 left hand	25 right hand	27 left hand	27 right hand	28 left hand	28 right hand	29 left hand	29 right hand	30 left hand	30 right hand	31 left hand	31 right hand	33 left hand	33 right hand
Tramline counter	1	1	1	1	1	1	1	1	1	1	1	0	1	1	1	1	1	1	1	1
	2	2	2	2	2	0	2	0	2	0	2	2	2	0	0	2	2	2	2	2
	0	3	3	0	3	3	3	3	3	3	0	3			3	3	0	3	3	3
	4	4	4	4	0	4	4	4	4	4	0	4			4	4	4	4	4	4
	5	5	5	5	5	5	5	5	0	5	5	5			5	0			0	5
	6	6	6	6	6	6	0	6	0	6	6	0			6	6			6	6
	7	0	0	7	0	7	7	7	7	7									7	7
	8	8	8	8	8	8	8	8	8	8									8	8
	9	9	9	9	9	0	0	9	9	0									9	9
	10	10	10	10	10	10	10	10	10	10									10	10
	11	11	11	11			11	11												
	12	0	0	12			12	12												
	13	13	13	13			13	0												
	14	14	14	14			14	14												
	15	15	15	15																
	0	16	16	0																
	17	17	17	17																
	18	18	18	18																

Fig. 23

Page 2  menu: machine data (Fig. 24):

-  during operation this sets the fan speed monitor (1/min.) at the level it is currently running.
-  Sets the fan speed monitor (1/min.) at the desired level it is intended to be monitored at.
-  Inputting the actual quantity of seed (kg) in the seed box
-  Inputting the refilled quantity (kg)
-  Setting residual amount (kg) left in the seed box at which the filling level alarm should be triggered.
- The **AMATRON<sup>+</sup>** triggers the alarm when
  - the theoretically calculated residual amount has been reached or
  - the seed box level sensor (option) is not covered with seed any more.

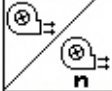
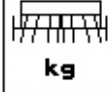
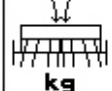


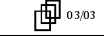


impe. rev. speed: 1500 U/min		prog. 
seed lev.: 203 kg		
fill machine hopper		
Alarm li.: 30 kg		
		alarm

Fig. 24

Page 3  menu: machine data (Fig. 25):

-  Setting the seed rate reduction (as %) necessary during tramline creation (see table Fig. 26, only applicable for machines without 'back to tank' seed return delivery).
-  Input of the regulation factor for the metering motors.  
standard value: 1

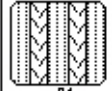

seed rate reduction at tramline: 25%		
control fac. 1.00		
		

Fig. 25




Working width	Number of seed coulters	Number of tramline coulters	 Recommended % seed rate reduction during tramline creation
3,0 m	24	4	17%
	30	4	13%
	24	6	25%
	30	6	20%
4,0 m	32	4	12%
	40	4	10%
	32	6	19%
	40	6	15%
4,5 m	36	4	11%
	44	4	9%
	36	6	17%
	44	6	14%
6,0 m	48	4	8%
	48	6	12%
8,0 m	64	4	6%
	64	6	9%
9,0 m	72	4	6%
	72	6	8%
12,0 m	96	4	4%
	96	6	6%

Fig. 26

### 5.2.1.1 Input of the sown and unsown distances (m) for the intermittent tramline



Setting the sowing distance (m) when the intermittent tramline function is switched on.



Setting the non-sowing distance (m) when the intermittent tramline function is switched on.

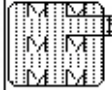

sown distance:	20 m	
n.sown distance:	20 m	

Fig. 27

#### 5.2.1.2 Calibration of forward speed sensor

For the adjustment of seed rate, the accumulation of the worked area or an indication of forward speed **AMATRON<sup>+</sup>** requires the impulses of the seed drill drive wheel over a measured distance of 100 m.

The value 'Imp./100m' is the number of impulses, that **AMATRON<sup>+</sup>** receives during the calibration distance from the seed drill drive wheel.

Slip on the seed drill drive wheel may vary in changeable soils (e.g. from heavy to light land) resulting in a change of the value of 'Imp./100m'.

It is necessary to determine the value 'Imp./100m':



- prior to the initial operation
- in changeable soils (wheel slip)
- in cases of a deviation between the seed rate determined by the calibration test and the quantity of seed applied in the field.
- in case of a deviation between the displayed and the actual area drilled.

For a manual input of that value for a subsequent operation in the same field the 'Imp./100 m' calibrated value can be entered into the table (Fig. 30).



The calibration figure "Imp./100m" may never be smaller than "250", as otherwise **AMATRON<sup>+</sup>** does not operate properly.

There are two potential possibilities to enter the 'Imp/100m' figure:

-  The value is known and is entered manually on the **AMATRON<sup>+</sup>** terminal
-  The value is unknown and will have to be determined by driving down a measured calibration distance of 100 m.

enter value for impulses/100m or calibrate automatically.	manual Entry
	Start



**Fig. 28**



Calibration travel by driving down a test distance:

- Carefully measure the test distance of 100 m in the field. Mark beginning and end of the test distance (Fig. 29).

Start

- Start calibration.
- Carefully drive the test distance from the beginning to the end mark (when driving off the counter jumps back to 0). The determined impulses are continuously shown on the display.
- Stop after 100 m. The display now shows the final determined number of impulses.
-  Input the value 'Imp./100m'. The value can be related to that tractor by selecting it from the memory.
-  Reject the new value 'Imp./100m'.

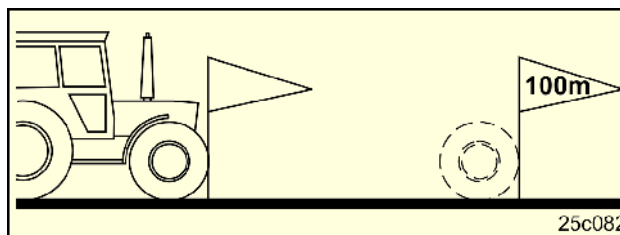


Fig. 29

The "Imp./100m" calibration value depends on both the seed drill model and the soil type.	<b>Cirrus / Citan</b> with gearbox	<b>Cirrus / Citan</b> with full electric metering
	<b>Calibration value "Imp./100 m"</b>	<b>Calibration value "Imp./100 m"</b>
Theoretical value	1187	742
Field 1		
Field 2		

Fig. 30













## 5.2.2 Creating a job

When the job menu is opened the last started (last worked) job appears.



20 jobs in maximum can be stored (Job no's.1-20).

 For creating a new job select the desired job no. (Fig. 28/1), then

-  Enter name
-  Enter note
-  all data in this existing job is deleted
-  Starting the job so that data for this job can be accumulated.
-  Enter desired application rate
-  Enter the kind of seed, the 1000-grain weight and the seed count..
-  Delete daily data
  - Worked area (ha/day)
  - Quantity applied (amount/day)
  - Working hours (hours/day)

 **Jobs that are already stored can be recalled with  and started with  once again.**

**Pressed shift key  (Fig. 32):**

-  Page forward in order.
-  Page backward in order

order No.:	6	Shift	name
name:	Betriebsanleitung		note
note:	Drillmaschine		delete
req.amou.:	15.00 kg/ha		start
kind of seed:	fine seeds		kg/ha K/n²
cal.gearbox pos.:	65.0		kind
order:			delete daily data
finish.ha:	15.00 ha		
hours:	5.0 h		
average:	2.50 ha/h		
sown rate:	225 kg		
trip data:			
area:	3.69 ha		
hours:	0.5 h		
amount	55 kg		

Fig. 31




Job No.:	25	Started		next job
Name:	Amazone			
Note:	instruction			PREV. job
Des.quantity:	200 kg/ha			
Finished area:	0.00 ha			
Hours:	0.0 h			
Average:	0.00 ha/h			
Quant.spread:	0 kg			
ha/day:	0.00 ha			
Amount/day:	0 kg			
Hours/day:	0.0 h			

Fig. 32



### 5.2.3 External job

Via a PDA computer an external job can be transferred into **AMATRON<sup>+</sup>** and started.  
This order always takes job number 21.  
The data transfer takes place via the serial interface.

-  finish external job.
-  Enter the required amount.

<b>Job No. :</b>	<b>20051</b>	finish external job
<b>Re. amount :</b>	<b>250 1/ha</b>	1/ha
<b>Worked ha:</b>	<b>0.00 ha</b>	
<b>Hours:</b>	<b>0.0 h</b>	
<b>Amount spra. :</b>	<b>0 Li.</b>	

Fig. 33

### 5.2.4 Calibration

The calibration test is carried out to ensure that during the sowing operation the desired seed rate is maintained.


Always carry out a calibration test

- when changing the seed type
- in cases with the same seed type, however, with different grain size, grain shape, bulk density or different dressing.
- when changing from the main seed wheel to the fine seed wheel and vice versa.
- in case of a deviation between the calibration test and the actual seed rate.

## 5.2.4.1 Calibration of the drill with remote seed rate control

Fill the seed hopper with sufficient seed.

As described in the operator's manual for the seed drill, place the collecting tray underneath the metering unit(s) and open the injector sluice(s).

 Check/enter the desired seed rate.

Tip:  
This figure can also be entered via the job menu (para. 5.2.2).

Press the  or  keys to set the gearbox lever to an estimated position

**Gearbox position "50": Sowing with the main metering wheels**

**Gearbox position "15": Sowing with the fine seed wheels**



The gearbox position which is indicated on the **AMATRON<sup>+</sup>** must coincide with that indicated on the gearbox setting scale.  
If not first calibrate the gearbox see para. 8.1.

- Close the inspection widow on the metering wheel.
- As described in the seed drill's operator's manual turn the star wheel with the aid of the calibration crank in direction of travel until all chambers of the metering wheels are filled with seed and an even seed flow is delivered into collecting tray(s).
- Empty the collecting tray(s).



-enter required seed rate -pre-select gearbox position -start calibration -turn crank at least until signal sounds -enter calibrated amount in kg		kg/ha K/m²
actually set: working width: 6.0 m req.amou.: 15.00 kg/ha gearbox position 62.5		 
		start calibr.


Fig. 34



Press and follow the advice on the display:

As described operator's manual of the seed drill turn the drive wheel with the aid of the crank until the horn sounds. **AMATRON<sup>+</sup>** registers any additional turns after the horn sounds in its calculation.

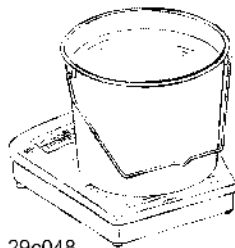
- to accept the calibration procedure after the horn

sounds, press the  key.

- Weigh the amount of seed collected in the collecting tray(s) (bear in mind the weight of the tray) and enter the weight (kg) into the terminal.



**Any balance used should weigh accurately as inaccuracy will cause deviations within the seed rate actually applied.**



29c048

**AMATRON<sup>+</sup>** automatically then calculates and sets the required gearbox position based on the calibration test data entered.

Repeat the calibration procedure to ensure the correct setting.



**When repeating the calibration use the newly determined gearbox position (do not use gearbox position 15 or 50).**

## 5.2.4.2 Calibration of the drill with full electric metering system

Fill the seed hopper with sufficient seed.

As described in the operator's manual for the seed drill, place the collecting tray underneath the metering unit(s) and open the injector sluice(s).



check/enter the desired seed rate.

Tip:

This figure can also be entered via the job menu (para. 5.2.2)



enter the proposed operational speed (km/h).



prior to the initial calibration set the Cal. Fac. (calibration factor) to 1.00 or a pre-calculated known value.




Prime the cells of the metering wheels once. The priming time can be adjusted and corresponds to the running time of the pre-charger system (see Fig. 40).

- Check whether the correct seed type has been selected.
- Close the inspection window on the metering wheel.
- Empty the collecting trays.



Press and follow the advice on the display:

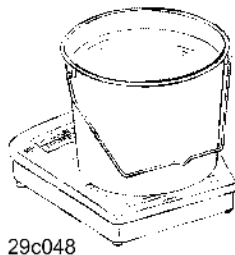
- Press  after the horn sounds to accept the calibration procedure.
- Weigh the amount of seed collected in the collecting tray(s) (bear in mind the weight of the tray) and enter the weight (kg) into the terminal.



**Any balance used should weigh accurately as inaccuracy will cause deviations within the seed rate actually applied.**

-enter required seed rate	kg/ha K/m²
-enter intended speed	km/h
-start calibration	start calibr.
-enter calibrated amount in kg	Cal. Fac.
actually set: working width: 6.0 m req.amou.: 15.00 kg/ha pre-sel.speed: 5 km/h calibration fac.: 1.05	X sec

Fig. 35



**AMATRON<sup>+</sup>** automatically then calculates the required calibration factor according to the entered calibration test data and sets the electric motor to the correct turning speed.

Repeat the calibration procedure to ensure the correct setting.

## 5.2.5 Setup


Applications in the Setup menu.

- Input and output of diagnosis data for customer service staff during maintenance work or in case of problems
- Changing the settings on the display
- Selecting and entering machine basic data or activating and isolating special options (for customer service staff only)



**The settings in the Setup menu are fundamental to the machine's function should only be carried out by qualified personnel.**



Page one  01/02 of menu: setup (Fig. 36):



Diagnosis of computer inputs (for customer service staff only)



Diagnosis of computer outputs (for customer service staff only).



Enter simulated speed (allows continued operation in spite of a defect in the forward speed sensor) (see para.9.2)



Terminal Setup (see para. 5.2.6).

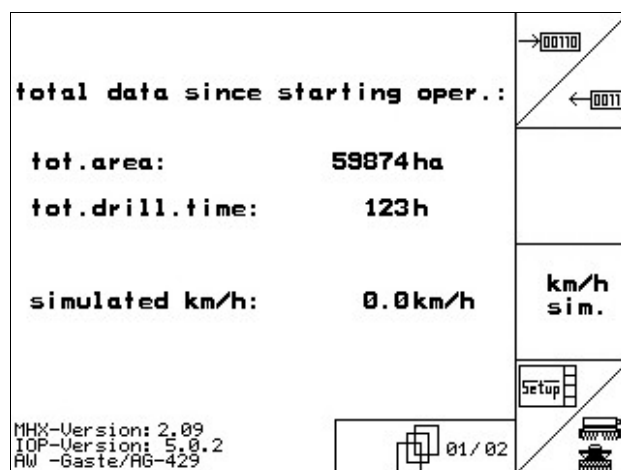



Fig. 36



select page one  01/04 of the basic data (Fig. 37):



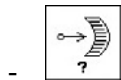
- Selection machine type



- Configure tramline system:

- Contractor
- Single tramline – actuation by linear tramline motor
- Double tramline – actuation by two linear tramline motors

The last selected value will be stored.



- Configure remote seed rate control

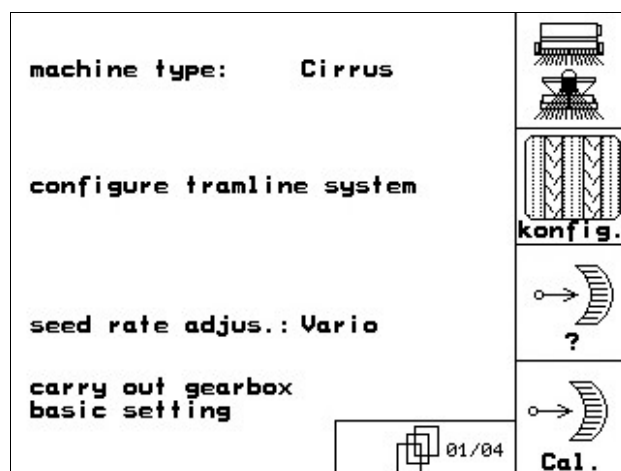





Fig. 37



-  Configure remote seed rate control:
  - no remote seed rate control
  - remote seed rate control via Vario gearbox
  - Full electric metering wheel drive
 The last selected value will be stored.
-  Enter number of metering procedures.
-  Calibrate gearbox (see para. 8.1).










seed rate adjus.: Vario	
number of metering procedures 1	
carry out gearbox basic setting	

Fig. 38

 Page 2  of the basic data (Fig. 39):

-  Number of bout marker sensors
  - one (one bout marker sensor registers the track marker position on drill models **-D9, AD, Avant, AD-P**)
  - none ( no bout marker sensor is fitted to the drill  
(input for drill models – **Cirrus / Citan**).
-  Rotary cultivator monitoring:
  - yes (PTO speed sensor exists)
  - no (PTO speed sensor does not exist).
-  Low level sensor in the seed hopper:
  - yes
  - no
-  Monitoring of metering wheels
  - yes
  - no.

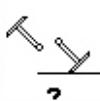













track marker sensors: one	
KG-rev.speed sen.: no	
seed level sen.: yes	
seed shaft sen.: yes	
	

Fig. 39



Page 3  of the basic data (Fig. 40):

-  Input of the delay time for metering wheel alarm
-  Input of the delay time for tramline system alarm
-  Input of the delay time of tramline lay shaft alarm (only possible on gravity seed drills)
-  Input of the running time (in seconds) of the pre-charging system.

alarm pe.seed shaft:	10s	 alarm
alarm pe.tramline:	10s	 alarm
alarm pe.stand still of the counter shaft at tramline:	10s	 alarm
run.time of the pre-met.device	10s	 running time

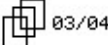











Fig. 40

Page 4  of the basic data (Fig. 41):

-  Input of the working width (m)
-  Pre emergence markers:
  - none
  - hydr. actuated
  - electr. actuated.

The last selected value will be stored
-  Alarm trigger limit when the fan speed deviates from the desired value (in %).
-  Wheel mark eradicators existing:
  - yes
  - no

working width:	6.0m	 m
pre-emerg.marker:	hydraulic	 ?
impelle.alarm limit	10%	 alarm
Eradicator:	no	 ?

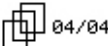



Fig. 41



Page two  02/02 of menu: setup (Fig. 42):



- Reset machine job computer to factory setting. All entered and accumulated data (orders, machine data, calibration values, Set Up data ) will get lost..

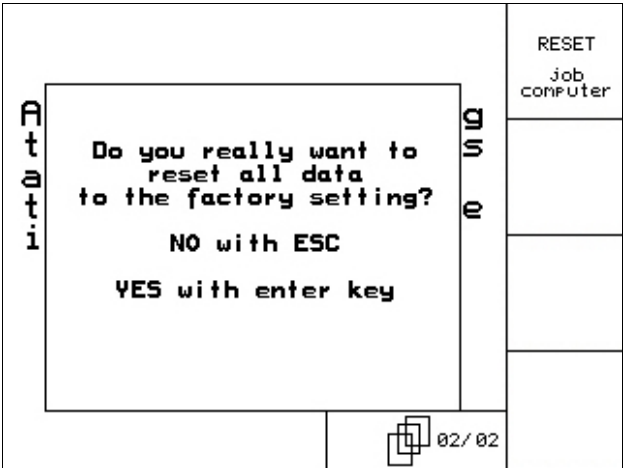






Fig. 42

## 5.2.6 Terminal Setup

To change the settings of the display, simultaneously press

- the page 
- shift  keys:
- Recall via the function icon  the entering "Display settings".
-  Indication of the implements on the Bus.

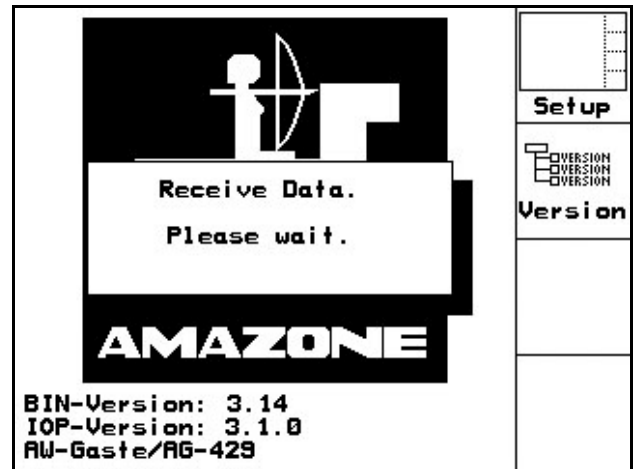







Fig. 43


 page 1  01/03 of the Terminal Setup

Via the entering "Display setting" you can change:

the contrast via the function icons  increase


contrast or  reduce contrast

the brightness via the function icons  increase

brightness or  reduce brightness


 Push button click sound On / Off

inverting the display black  $\leftarrow \rightarrow$  white via the function

icon 

the language of the operator terminal via the function icon



deletion of the stored data via the function icon 

 Leave menu Terminal Setup



**The actuation of the function Terminal-Reset resets all the terminal data to the factory settings. No machine data will get lost.**

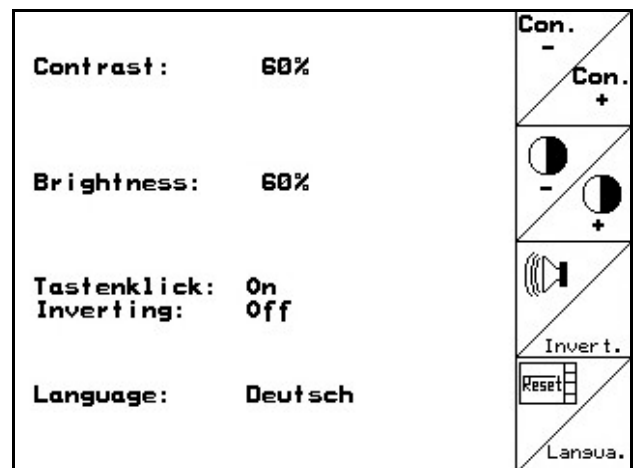


Fig. 44

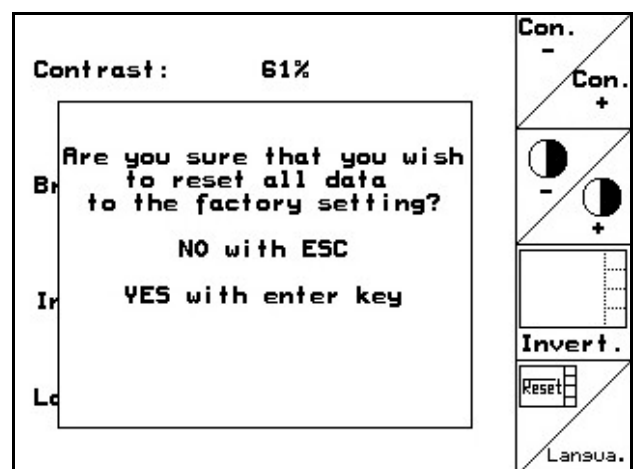





Fig. 45



Page 2 02/03 Terminal Setup

-  Input of time
-  Input of date
-  R5232 Input of data transfer baud speed






<b>Time</b>	<b>10 : 12 : 53</b>	 <table border="1"> <tr><td>1</td><td>2</td><td>3</td><td>4</td><td>5</td></tr> <tr><td>6</td><td>7</td><td>8</td><td>9</td><td>10</td></tr> <tr><td>11</td><td>12</td><td>13</td><td>14</td><td>15</td></tr> <tr><td>16</td><td>17</td><td>18</td><td>19</td><td>20</td></tr> <tr><td>21</td><td>22</td><td>23</td><td>24</td><td>25</td></tr> <tr><td>26</td><td>27</td><td>28</td><td>29</td><td>30</td></tr> </table>	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30
1	2		3	4	5																											
6	7		8	9	10																											
11	12	13	14	15																												
16	17	18	19	20																												
21	22	23	24	25																												
26	27	28	29	30																												
<b>Date:</b>	<b>04 . 01 . 2006</b>																															
<b>R5232 :</b>	<b>57600 Baud (nicht Prog.-Modus)</b>																															
		 <b>R5232</b>																														
		02/03																														

Fig. 46

Page 3 03/03 Terminal Setup

- Deletion of programme:
- 
- 1.  ,  Selection of programme.
- 2.  löschen Deletion of programme


Please select the program via the "up" and "down" keys		 delete
<b>Program:</b>	<b>SPR36DE</b>	
<b>Size:</b>	<b>78kByte</b>	
<b>Empty memory:</b>	<b>448kByte</b>	
		03/03

Fig. 47

## 6. Operation in the field

Before starting sowing the **AMATRON<sup>+</sup>** will need to be provided with the following data:

- Job data (see para. 5.2.2)
- Machine data (see para. 5.2.1)
- Calibration test data (see para. 5.2.3).

During operation the seed rate can be changed at random with the press of a key.



each press of this key increases the sowing rate by the preset quantity step (para.5.2.1) across the full drill (e.g:+10%).



Reset the sowing rate back to 100% across the full drill.



each press of this key reduces the sowing rate by the preset quantity step (para.5.2.1) across the full drill (e.g:-10%).

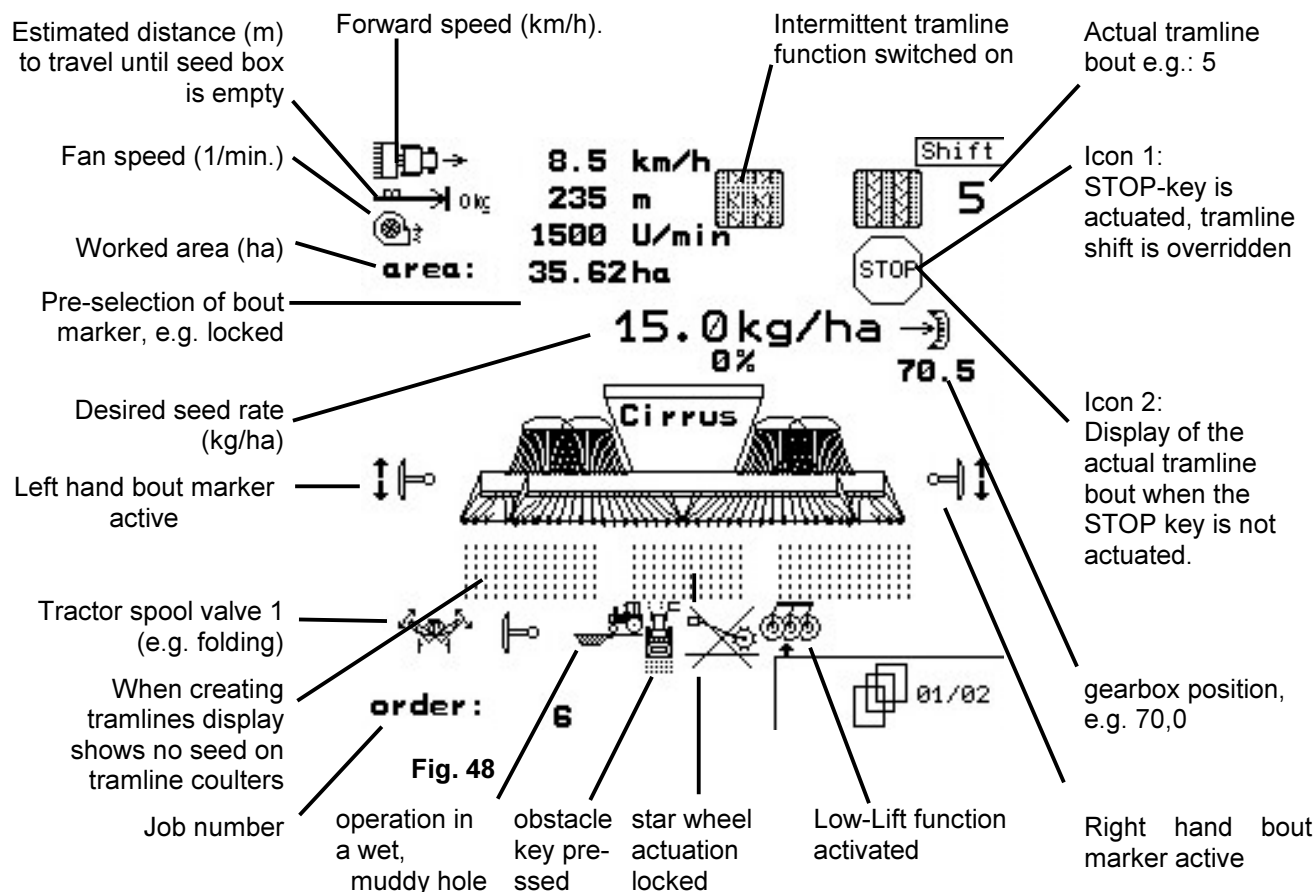


Ensure that **AMATRON<sup>+</sup>** is switched off during transport to the field and when travelling on public roads!



## 6.1 Cirrus with Vario gearbox




### 6.1.1 Display – operational menu Cirrus with Vario gearbox



#### Wheel track eradicators (option).





The functions not selected are missing on the display.

## 6.1.2 Advice on field operation

-  switch **AMATRON<sup>+</sup>** on.
- Select the desired job from the main menu and re-check the settings
-  start job
-  select operational menu

For actuating the operational functions three tractor spool valves are utilised:

- When actuating tractor spool valve 1 (hose marking yellow) the following functions are activated:
  - Lowering machine
  - Bringing the star wheel into operational position.
  - Bringing the pre-selected bout marker into operational position ( check the indicated tramline bout counter for the first circuit of the field and correct if necessary).
- Depending on function selected tractor spool valve 2 (hose marking green) controls the following functions at random:

-  folds the machine's wing out
-  brings the cultivator disc elements into operational position
-  brings wheel track eradicators (option) into operational position
-  pressurises the hydraulic ram for the extra coverage following harrow.

- When actuating tractor spool valve 3 (hose marking red), the fan is switched on or off.

- Start sowing operation.
  - After approx. 30 m stop and check:
    - Operational intensity of the cultivator disc elements
    - Placement depth of the seed
    - Operational intensity of the extra coverage following harrow.
  - During the sowing operation **AMATRON<sup>+</sup>** displays the operational menu and from here all the sowing operation functions can be actuated. .
- The accumulating data are stored within the started job.

### After finishing operation:

Check job data (if wanted).

Activate tractor spool valves if required.








-  switch **AMATRON<sup>+</sup>** off.











### 6.1.3 Key layout: Operational menu Cirrus with Vario gearbox








Page 1: operational menu (Fig. 49):

-  manual pre-selection of bout marker (only actuate this when the machine is lifted!)
  -  (left hand side)
  -  (right hand side)
  -  (both)
  -  (locked).
  -  Shuttle operation
-  Shifting on track marker at shuttle operation (only actuate this when the machine is lifted!)
 

+1  +1  +1  +1  +1  +1  +1  +1  +1



If necessary the function key  allows the shifting on of the track marker at shuttle operation.

-  Lift the machine with control unit 1 (hose mark yellow) (the other functions on control unit 1 are blocked).  
Eases the weight off the packer roller in fields with mud holes. During operation the machine rests on the extended integrated transport tyres.
-  Lifting/lowering the active track marker with control unit 1 (hose mark yellow) (the other functions on control unit 1 are blocked)  
When passing obstacles in the field the active bout marker can be swung in and then, by actuating the spool valve in the opposite direction, swung out after the obstacle has been passed.
-  -1 Scroll back the tramline counter.
-  +1 Scroll forward the tramline counter

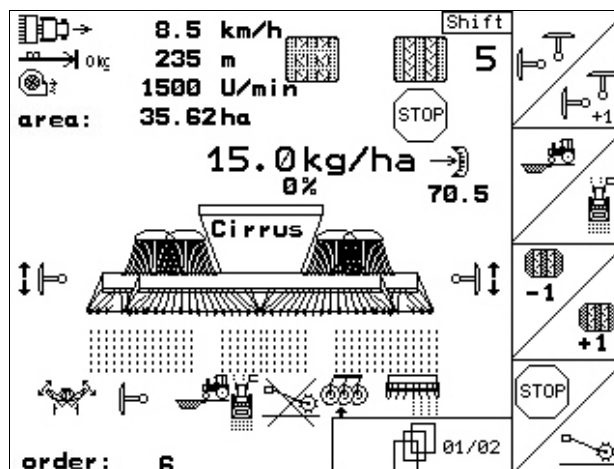




Fig. 49










-  Switch on or off the tramline counter (Stop-key)

-  Lock the actuation of the star wheel.

When the machine is lowered the star wheel is kept in the lifted position.

 Page 2: operational menu (Fig. 50):

-  Switching on / off the left hand side part width section shut-off, (option on Cirrus 6000)
-  Switching on / off the right hand side part width section shut-off, (option on Cirrus 6000)
-  Pre-selecting the actuation of the wheel mark eradicators (option)
-  Pre-selecting the adjustment of the cultivation disc elements
-  Pre-selecting the increase / reduction of the exact harrow pressure
-  Switching on / off the intermittent tramline function
-  Pre-selecting the 'Low-Lift' function: the coulter frame lift is locked when the machine is raised, e.g. when turning at the headlands (The 'Low-Lift' function is not allowed during road transport as the coulter frame has to be lifted entirely).

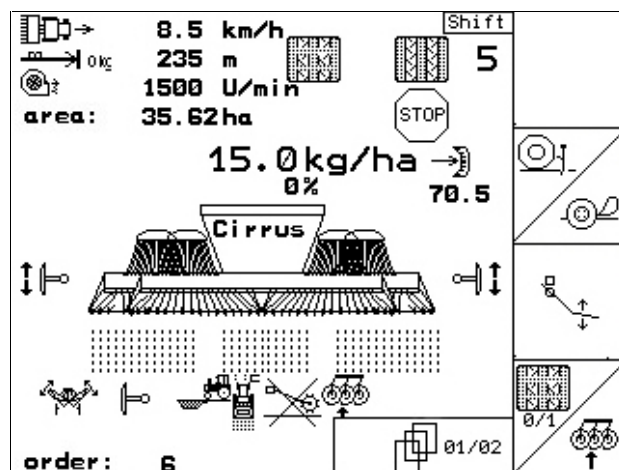


Fig. 50



**Shift key pressed**

(possible from page 1 and page 2, Fig. 51):



Folding in and out the wings.

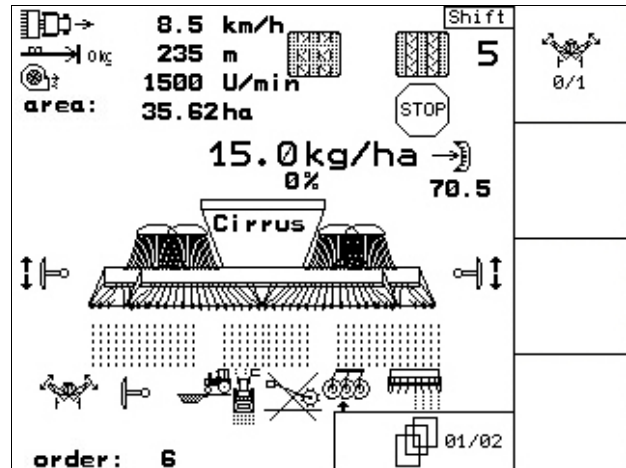


Fig. 51

#### 6.1.4 Layout menu - joystick

##### Cirrus

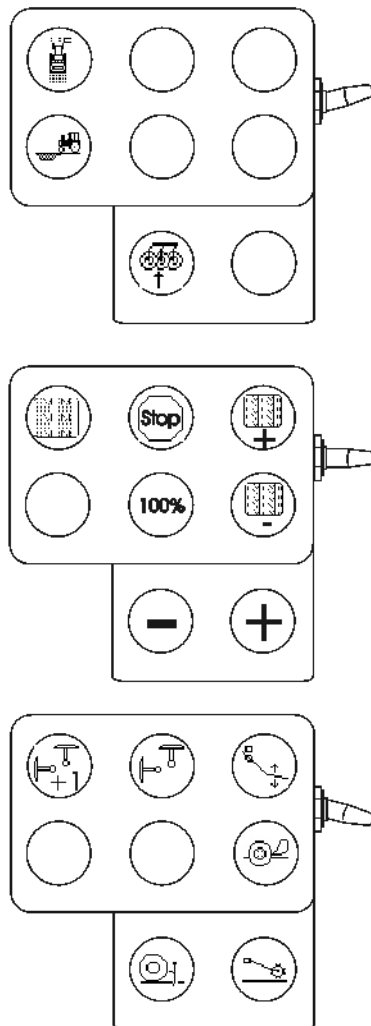
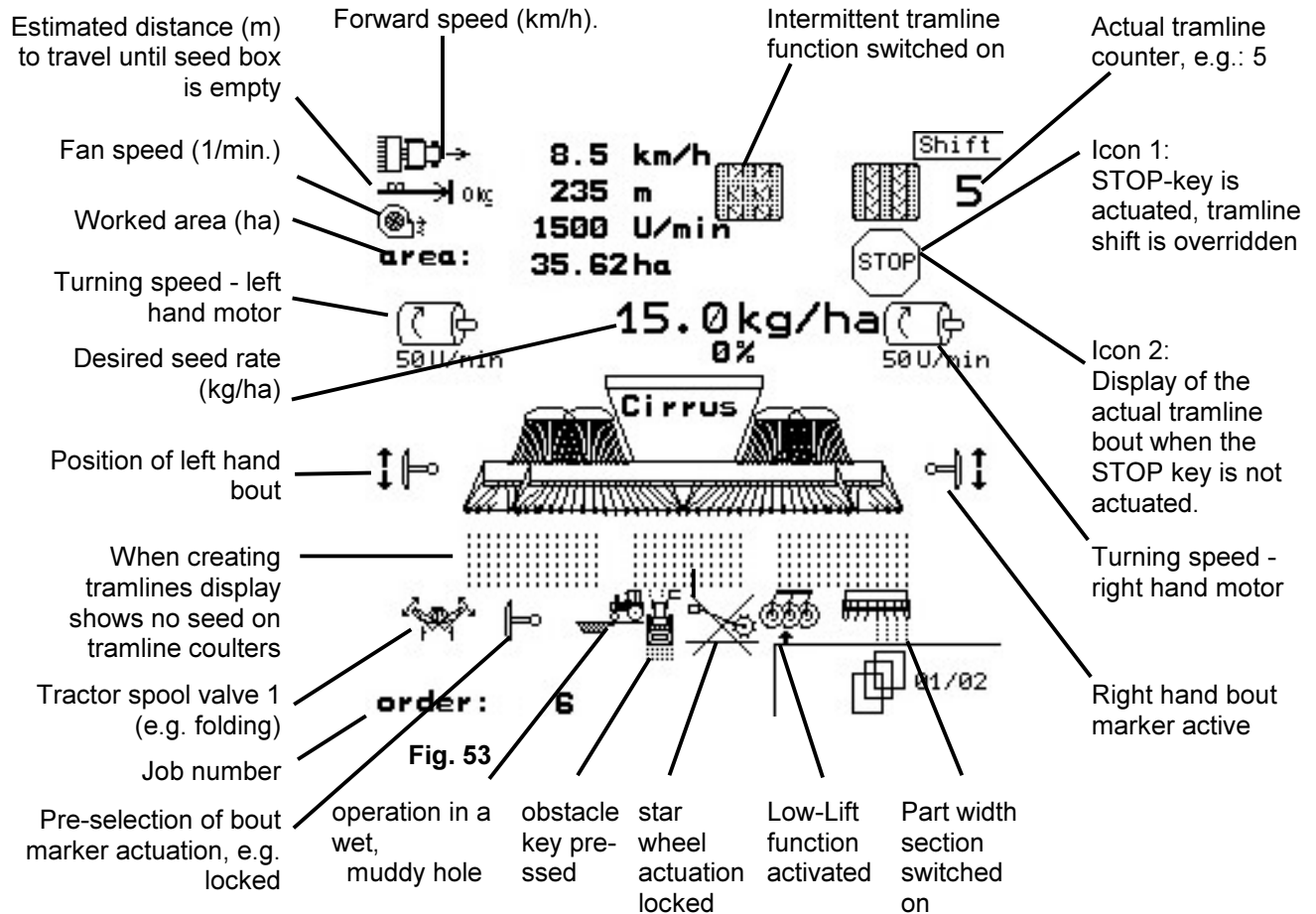


Fig. 52

## 6.2 Cirrus with full electric metering system

### 6.2.1 Display – operational menu Cirrus with full electric metering system



**Part width section shut-off not possible on Cirrus 3000 and Cirrus 4000.**


**wheel track eradicators (option).**

The functions not selected are missing on the display.







-  switch **AMATRON<sup>+</sup>** on.
- Select the desired job from the main menu and re-check the settings

-  start job

-  select operational menu

For actuating the operational functions three tractor spool valves are utilised:

- When actuating tractor spool valve 1 (hose marking yellow) the following functions are activated:
  - Lowering machine
  - Bringing the star wheel into operational position
  - Bringing the pre-selected bout marker into operational position (check the indicated tramline bout counter for the first circuit of the field and correct if necessary)
- Depending on function selected tractor spool valve 2 (hose marking green) controls the following functions at random:

-  folds the machine's wing out
-  brings the cultivator disc elements into operational position
-  brings wheel track eradicators (option) into operational position
-  pressurises the hydraulic ram for the extra coverage following harrow.

- When actuating tractor spool valve 3 (hose marking red) , the fan is switched on or off.

- Start sowing operation.  
When the star wheel has been lowered into work, the automatic driving of the pre-charger starts with half the operational speed as entered from para. 5.2.4.1



The pre-charging can be over-ridden prematurely.

- After approx. 30 m stop and check:
  - Operational intensity of the cultivator disc elements
  - Placement depth of the seed
  - Operational intensity of the extra coverage following harrow.
- During the sowing operation **AMATRON<sup>+</sup>** displays the operational menu and from here all the sowing operation functions can be actuated. .

The accumulating data are stored within the started job.

#### After finishing operation:

Check job data (if wanted).

Activate tractor spool valves if required.


-  switch **AMATRON<sup>+</sup>** off.




## 6.2.2 Key description: Operational menu


### Cirrus with full electric metering system




Page 1: operational menu (Fig. 54):







-  manual pre-selection of bout marker (only actuate this when the machine is lifted!)

-  (left hand side)
-  (right hand side)
-  (both)


-  (locked).


-  Shuttle operation


-  pre-selection during the shuttle operation (only actuate this when the machine is lifted!)


+1  +1  +1  +1  +1  +1  +1





If necessary the function key  allows the shifting on of the track marker at shuttle operation.

-  Lift the machine with control unit 1 (hose mark yellow) (the other functions on control unit 1 are blocked). Eases the weight off the packer roller in fields with mud holes. During operation the machine rests on the extended integrated transport tyres.

-  Lifting/lowering the active track marker with control unit 1 (hose mark yellow) (the other functions on control unit 1 are blocked). When passing obstacles in the field the active bout marker can be swung in and then, by actuating the spool valve in the opposite direction, swung out after the obstacle has been passed.

-  Scroll back the tramline counter.

-  Scroll forward the tramline counter

-  Switch on or off the tramline counter (Stop-key)

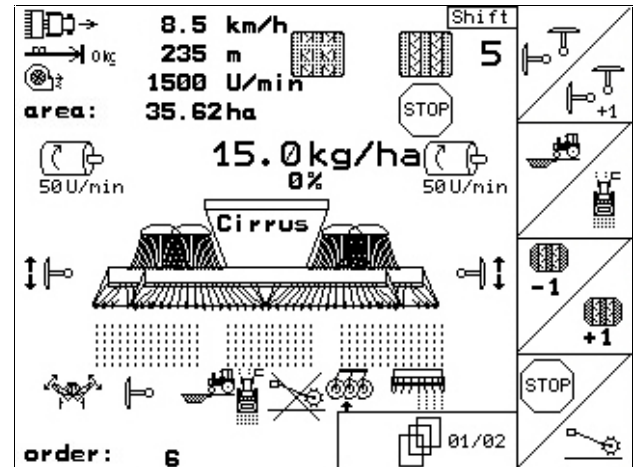
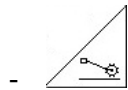


Fig. 54

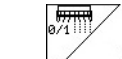


- Lock the actuation of the star wheel

When the machine is lowered the star wheel is kept in the lifted position.



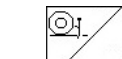
Page 2: Operational menu (Fig. 55):



- Switching on / off the left hand side part width section shut-off, (option on **Cirrus 6000**)



- Switching on / off the right hand side part width section shut-off, (option on **Cirrus 6000**)



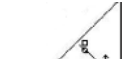
- Pre-selecting the actuation of the wheel mark eradicators (option)



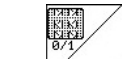
- Pre-selecting the adjustment of the cultivation disc elements



- Starts the pre-charging (see chap. 5.2.5.)



- Pre-selecting the increase / reduction of the exact harrow pressure



- Switching on / off the intermittent tramline function



- Pre-selecting the 'Low-Lift' function: the coulter frame lift is locked when the machine is raised, e.g. when turning at the headlands (The 'Low-Lift' function is not allowed during road transport as the coulter frame has to be lifted entirely).

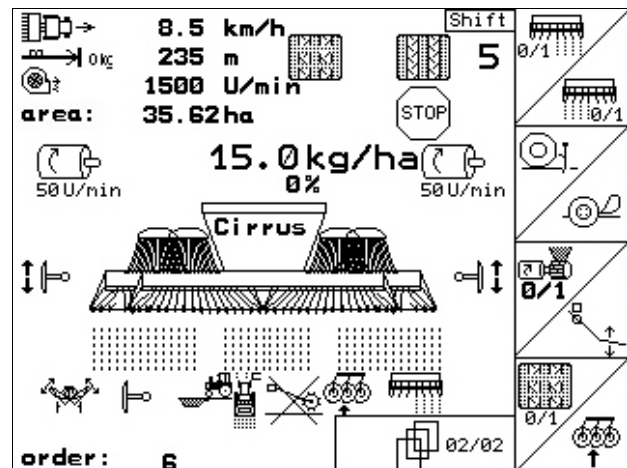


Fig. 55



Shift key pressed

(possible from page 1 and page 2, Fig. 51):



Folding in and out the wings.

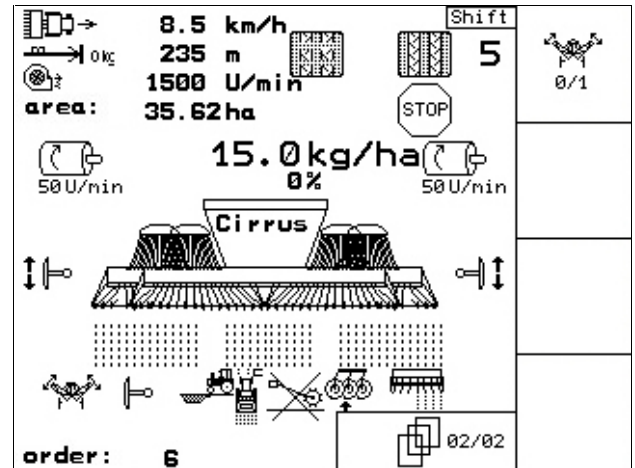


Fig. 56

## 6.2.3 Layout menu - joystick

### Cirrus

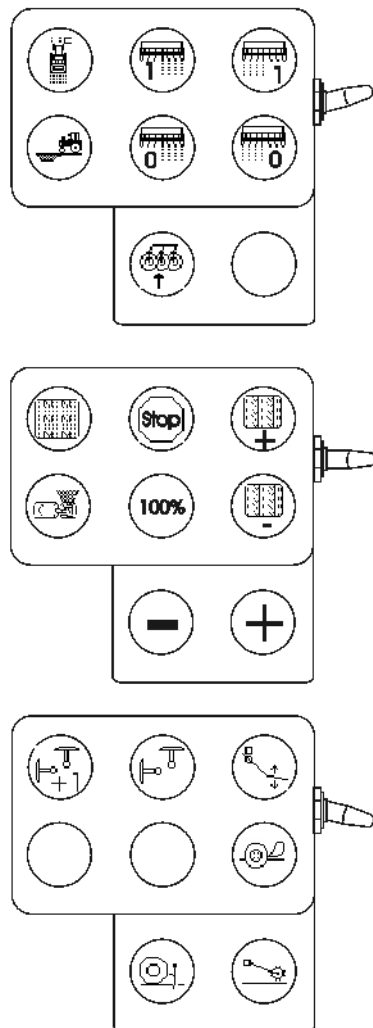
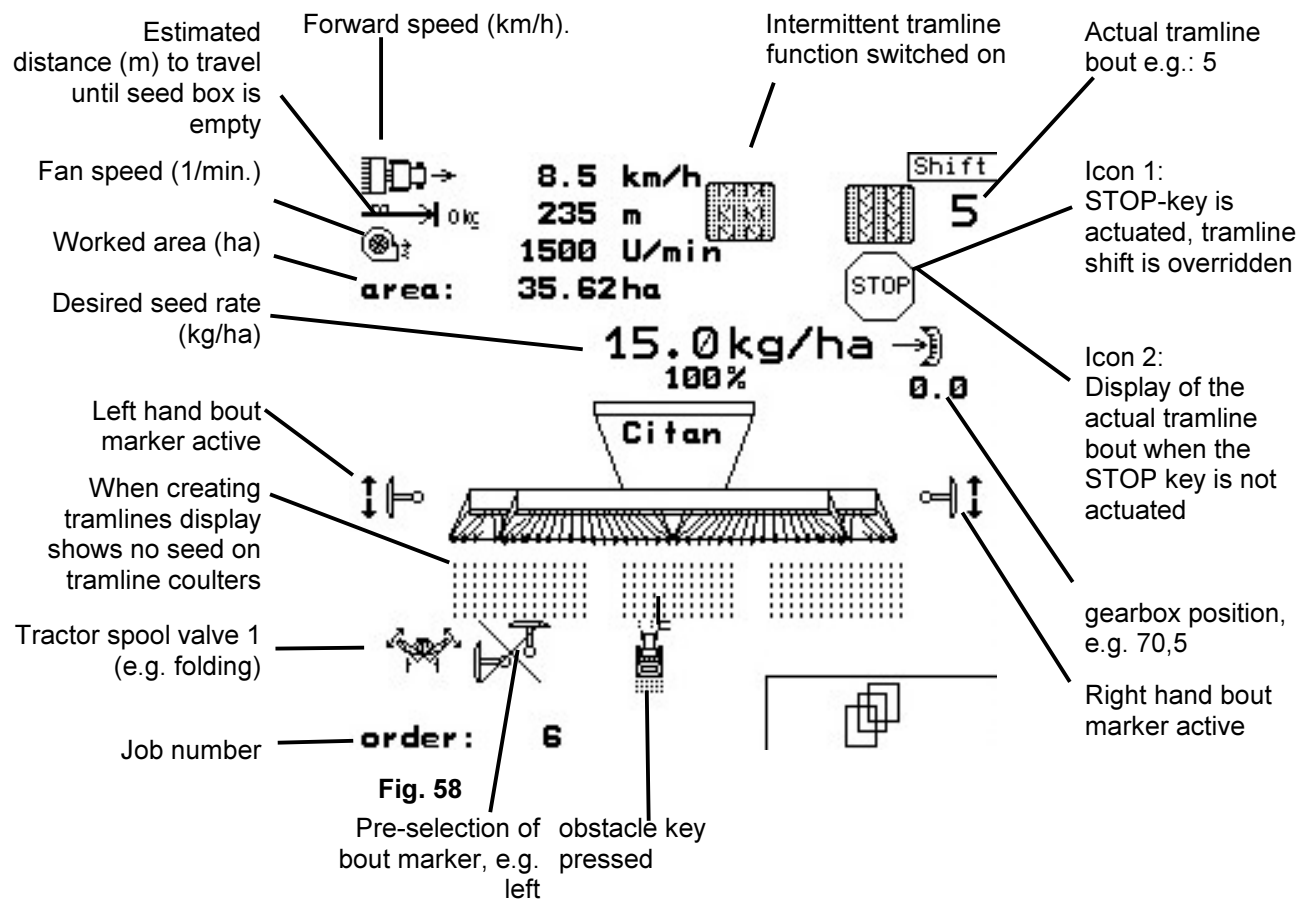


Fig. 57






### 6.3 Citan with Vario gearbox

#### 6.3.1 Display – operational menu Citan with Vario gearbox






### 6.3.2 Advice on field operation

-  switch **AMATRON<sup>+</sup>** on.
- Select the desired job from the main menu and re-check the settings
-  start job
-  select operational menu

For actuating the operational functions three tractor spool valves are utilised:

- When actuating tractor spool valve 1 (hose marking yellow) the following functions are activated:
  - Lowering machine
  - Bringing the star wheel into operational position
  - Bringing the pre-selected bout marker into operational position ( check the indicated tramline bout counter for the first circuit of the field and correct if necessary)
- Depending on function selected tractor spool valve 2 (hose marking green) controls the following functions at random:
  -  folds the machine's wing out
- When actuating tractor spool valve 3 (hose marking red), the fan is switched on or off.

- Start sowing operation.
  - After approx. 30 m stop and check:
    - Operational intensity of the cultivator disc elements
    - Placement depth of the seed
    - Operational intensity of the extra coverage following harrow.
  - During the sowing operation **AMATRON<sup>+</sup>** displays the operational menu and from here all the sowing operation functions can be actuated. .
- The accumulating data are stored within the started job.

#### After finishing operation:

Check job data (if wanted).

Activate tractor spool valves if required.








-  switch **AMATRON<sup>+</sup>** off.












### 6.3.3 Key layout: Operational menu **Citan** with Vario gearbox








Page 1: operational menu (Fig. 59):

-  manual pre-selection of bout marker (only actuate this when the machine is lifted!)
  -  (left hand side)
  -  (right hand side)
  -  (both)
  -  (locked).
  -  Shuttle operation
-  Shifting on track marker at shuttle operation (only actuate this when the machine is lifted!)
 

+1  +1  +1  +1  +1  +1  +1  +1  +1  +1



If necessary the function key  allows the shifting on of the track marker at shuttle operation.

-  Lifting/lowering the active track marker with control unit 1 (hose mark yellow) (the other functions on control unit 1 are blocked).  
When passing obstacles in the field the active bout marker can be swung in and then, by actuating the spool valve in the opposite direction, swung out after the obstacle has been passed).
-  Scroll back the tramline counter.
-  Scroll forward the tramline counter
-  Switch on or off the tramline counter (Stop-key)

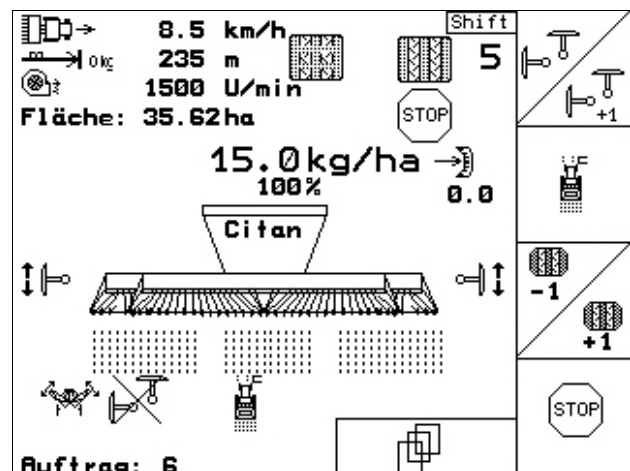


Fig. 59



Page 2: operational menu (Fig. 60)



- Switching on / off the intermittent tramline function

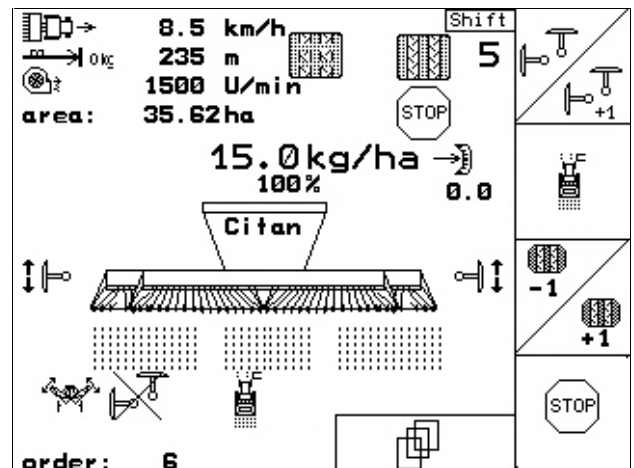


Fig. 60



Shift key pressed

(possible from page 1 and page 2, Fig. 61):



- Folding in and out the wings.

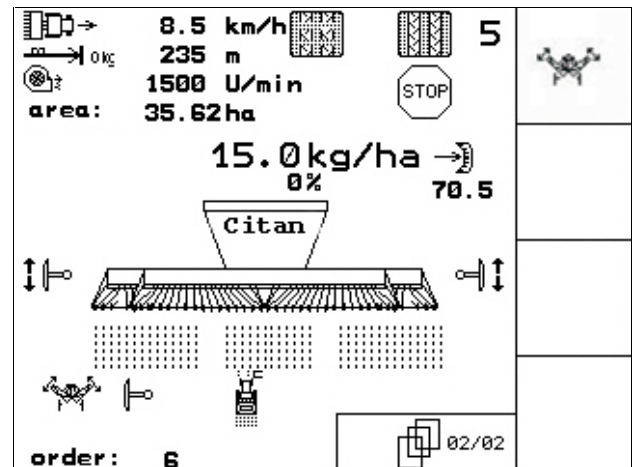


Fig. 61

### 6.3.4 Layout menu - joystick

**Citan** with gear box

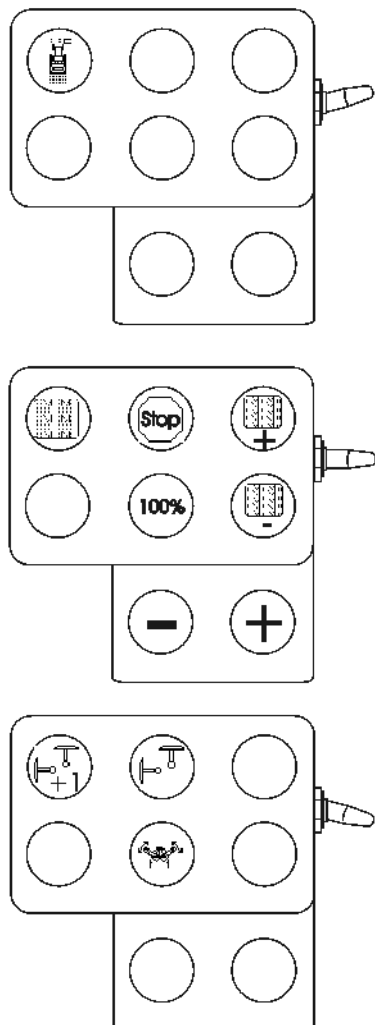
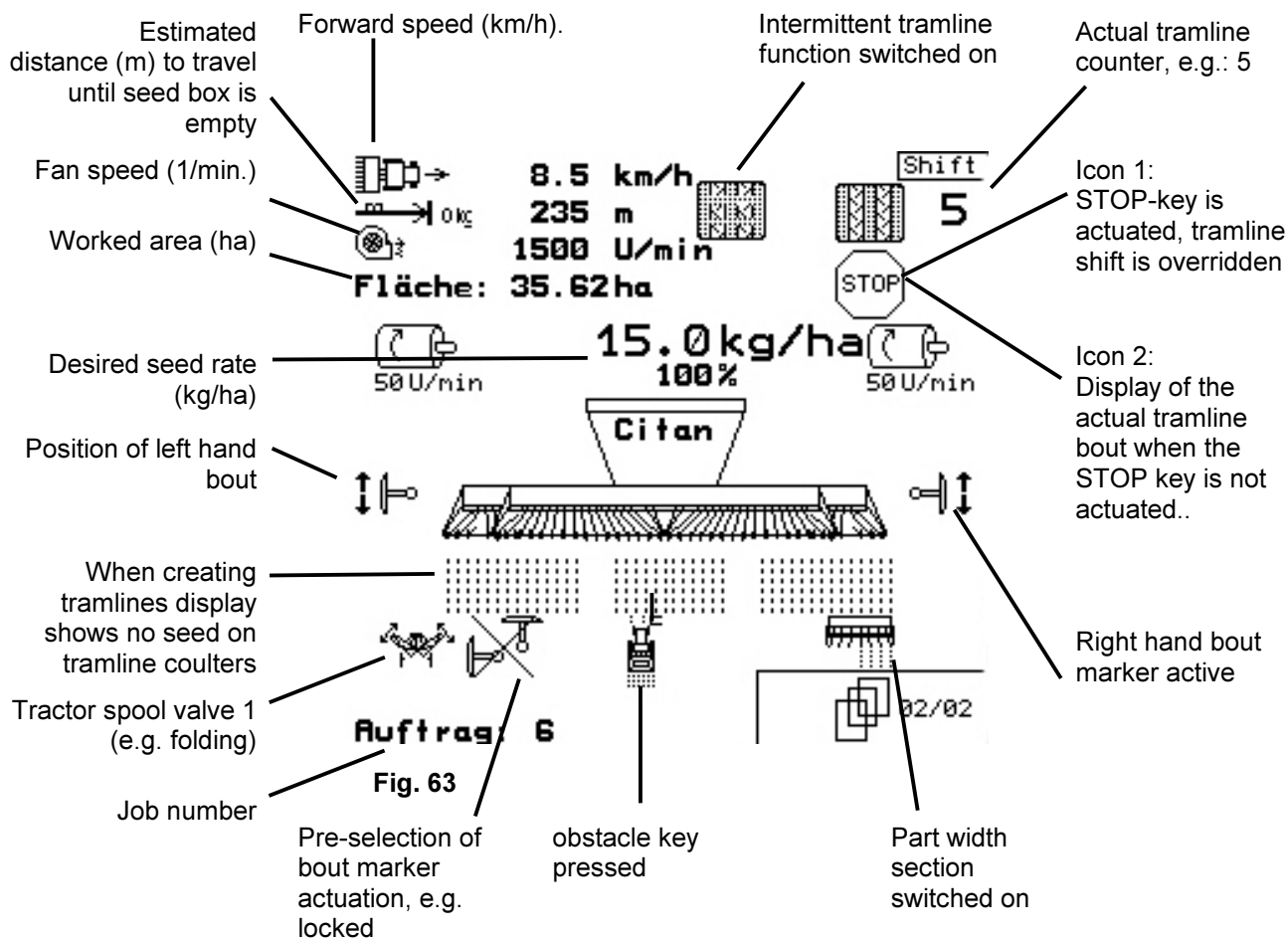


Fig. 62

## 6.4 Citan with full electric metering system

### 6.4.1 Display – operational menu Citan with full electric metering system




#### Wheel track eradicators (option).

The functions not selected are missing on the display.




-  switch **AMATRON<sup>+</sup>** on.
- Select the desired job from the main menu and re-check the settings

-  start job

-  select operational menu

For actuating the operational functions three tractor spool valves are utilised:

- When actuating tractor spool valve 1 (hose marking yellow) the following functions are activated:
  - Lowering machine
  - Bringing the star wheel into operational position.
  - Bringing the pre-selected bout marker into operational position (check the indicated tramline bout counter for the first circuit of the field and correct if necessary).
- Depending on function selected tractor spool valve 2 (hose marking green) controls the following functions at random:
  -  folds the machine's wing out
- When actuating tractor spool valve 3 (hose marking red) , the fan is switched on or off.

- Start sowing operation.  
When the star wheel has been lowered into work, the automatic driving of the pre-charger starts with half the operational speed as entered from para. 5.2.4.1



The pre-charging can be over-ridden prematurely.

- After approx. 30 m stop and check:
  - Operational intensity of the cultivator disc elements
  - Placement depth of the seed
  - Operational intensity of the extra coverage following harrow.
- During the sowing operation **AMATRON<sup>+</sup>** displays the operational menu and from here all the sowing operation functions can be actuated.

The accumulating data are stored within the started job.

#### After finishing operation:

Check job data (if wanted).














Activate tractor spool valves if required.

-  switch **AMATRON<sup>+</sup>** off.


## 6.4.2 Key description: Operational menu **Citan** with full electric metering system







Page 1: operational menu (Fig. 64):

-  manual pre-selection of bout marker  
(only actuate this when the machine is lifted!)
  -  (left hand side)
  -  (right hand side)
  -  (both)
  -  (locked).
  -  Shuttle operation
  -  Shifting on track marker at shuttle operation  
(only actuate this when the machine is lifted!)
- +1      



If necessary the function key  allows the shifting on of the track marker at shuttle operation.

-  Lifting/lowering the active track marker with control unit 1 (hose mark yellow)  
(the other functions on control unit 1 are blocked)  
When passing obstacles in the field the active bout marker can be swung in and then, by actuating the spool valve in the opposite direction, swung out after the obstacle has been passed.).
-  Scroll back the tramline counter.
-  Scroll forward the tramline counter
-  Switch on or off the tramline counter (Stop-key)

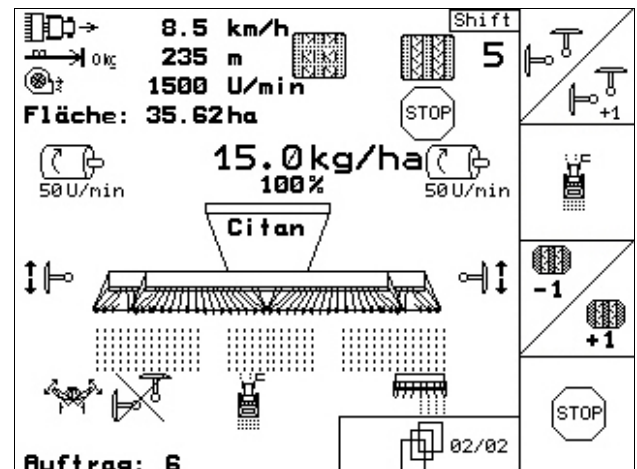






Fig. 64




Page 2: Operational menu (Fig. 65)

-  Switching on / off the left hand side part width section shut-off, (option)
-  Switching on / off the right hand side part width section shut-off, (option)
-  Starts the pre-charging (see chap. 5.2.5.)
-  Switching on / off the intermittent tramline function



Shift key pressed

(possible from page 1 and page 2, Fig. 66):

-  Folding in and out the wings

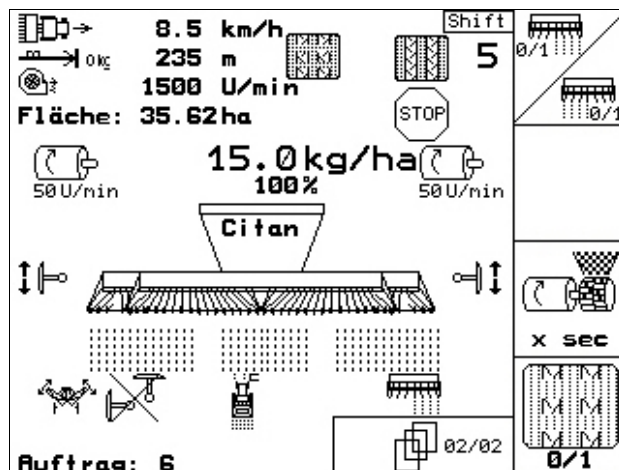


Fig. 65

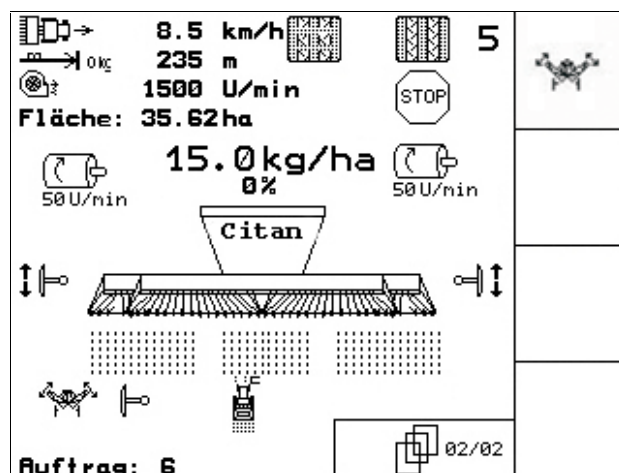


Fig. 66



## 6.4.3 Layout menu - joystick

**Citan** with full electric metering system

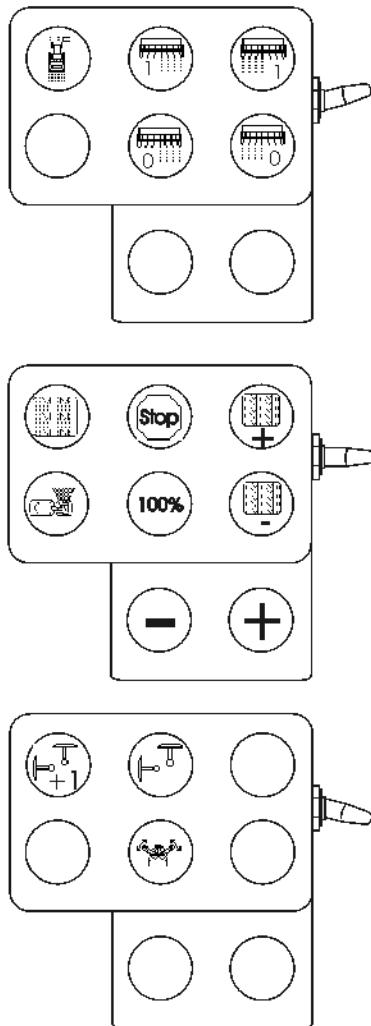


Fig. 67

## 7. Joystick

### 7.1 Fitting

Attach the joystick (Fig. 68/1) by using 4 bolts within convenient reach in the tractor cab.

Insert the plug of the basic equipment into the 9-pin Sub-D socket of the joystick (Fig. 68/2).

Insert the plug (Fig. 68/3) of the joystick into the mid Sub-D socket of **AMATRON<sup>+</sup>**

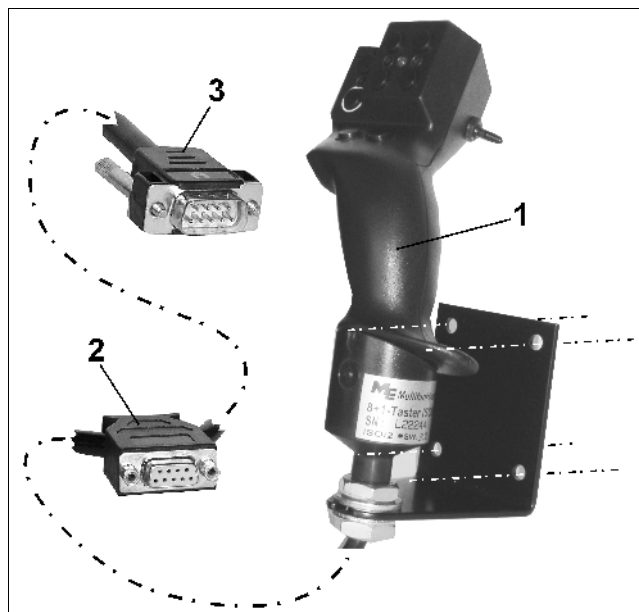





Fig. 68

### 7.2 Function




The joystick only functions in the operational menu of **AMATRON<sup>+</sup>**. It allows the blind actuation of **AMATRON<sup>+</sup>** during operation in the field.

For the actuation of **AMATRON<sup>+</sup>** the joystick (Fig. 69) provides 8 keys (1 – 8). In addition the coverage of the keys can be changed 3 times by the switch (Fig. 70/2).

As standard the switch is in the

-  mid position (Fig. 70/A) and can be moved
-  upwards (Fig. 70/B) or
-  downwards (Fig. 70/C).

The position of the switch is indicated by a LED light (Fig. 70/1).

-  LED-indication yellow
-  LED-indication red
-  LED-indication green

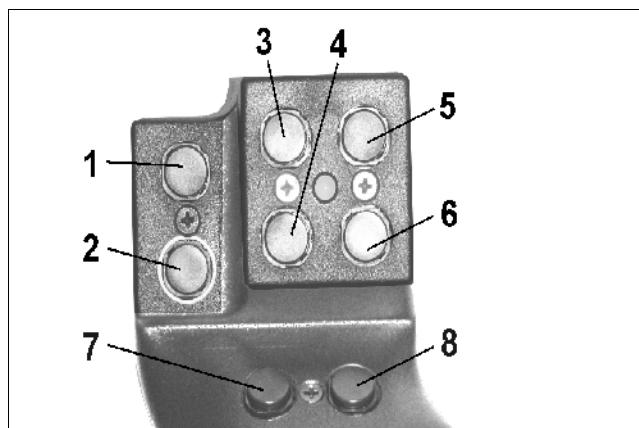


Fig. 69

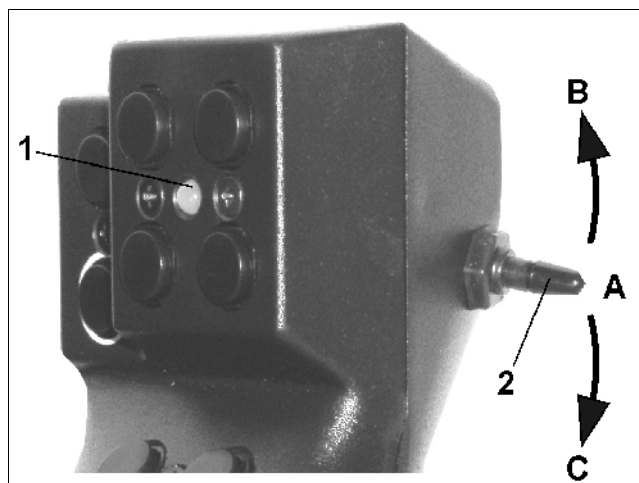


























Fig. 70

## 7.3 Key layout

	<b>Cirrus</b> with Vario gearbox	<b>Cirrua</b> with full electric metering	<b>Citan</b> with Vario gearbox	<b>Citan</b> with full electric metering
1 	obstacles -function			
2 	mud hole -function			
3 		Switching on the left hand part width shut-off	Switching on the left hand part width shut-off	
4 		Switching off the left hand part width shut-off	Switching off the left hand part width shut-off	
5 		Switching on the right hand part width shut-off	Switching on the right hand part width shut-off	
6 		Switching off the right hand part width shut-off	Switching off the right hand part width shut-off	
7 	Low-Lift-function			
8 				
1 	Switching on / off the intermittent tramline function			
2 		Pre-selecting the increase		Pre-selecting the increase
3 	Switch on or off the tramline counter (Stop-key)			
4 	quantity 100%			
5 	Scroll forward the tramline counter (+1)			
6 	Scroll back the tramline counter (-1)			
7 	- quantity [%]			
8 	+ quantity [%]			
1 	Shifting on track marker at shuttle operation left hand / right hand			
2 				
3 	Switching on / off the right hand part width shut-off			
4 			Switching the hydraulic valve to actuate the bout markers —	
5 	Pre-selection harrow pressure			
6 	Pre-selection working depth discs			
7 	Actuate pre-selection track marker			
8 	Lock pre-selection the star wheel			



8. Maintenance

8.1 Calibration of gearbox  
(not required for machines with full electric metering)

Calibrating seed drills which are equipped with the Vario gearbox:




- prior to initial operation if **AMATRON<sup>+</sup>** has not been factory fitted to the machine, but has been retrofitted..
- in case of a deviation between the display on the terminal and the gearbox scale.



Page 1 – menu: setup.



Calibration of gearbox:

-  move the gearbox lever back to zero until the LED on the electric seed rate control motor lights up.
-  take the gearbox setting lever to a figure larger than 80 on the scale
-  Confirm the setting and enter the figure that is indicated, on the scale, by the gearbox setting lever in the now open input block (Fig. 72)



**Read the figure off the scale only when directly in front in order to avoid any reading errors.**

- After the calibration procedure move the gearbox to another figure. The indicated value should correspond to the scale value.

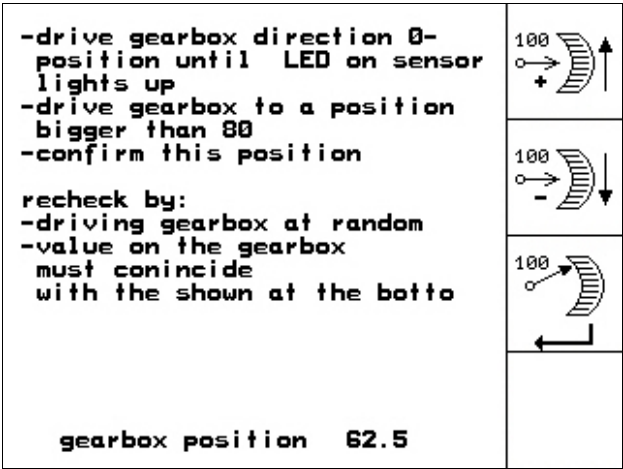


Fig. 71

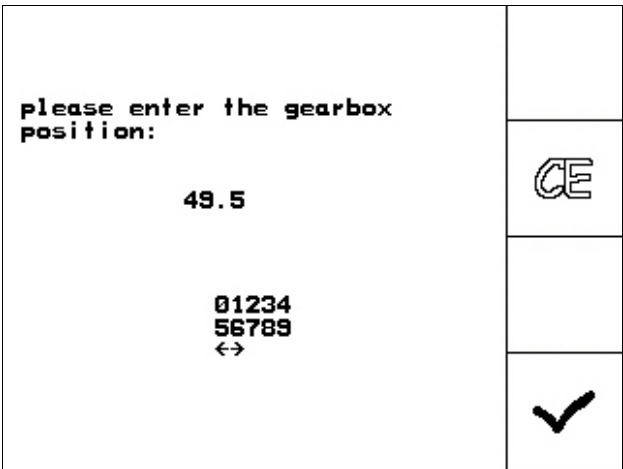


Fig. 72

## 9. Help menu

The help menu is opened from the main menu:



help menu:

- 1

 help on operation
- 2

 help on fault messages
- 3

 help on tramline creation

<b>aid</b>	
<b>1.aid for actuation</b>	<b>1</b>
<b>2.aid for fault messages</b>	<b>2</b>
<b>3.tramline rhythms</b>	<b>3</b>

Fig. 73



10. Malfunction

10.1 Alarm

Warning message:

A warning message (Fig. 74) appears at the bottom of the display and the audible alarm sounds three times. Remedy fault as soon as possible.

Example:



Warning: Seed hopper contents low.  
Remedy: Refill seed hopper.

machine type:	Cirrus	Order
order No.:	6	drill calibr.
tramline rhythm No.:	15	machine
working width:	6.0m	Setup
level too low		

Fig. 74

Error message:

The error message (Fig. 75) appears in the middle of the display and the audible alarm sounds.

- Read alarm message on the display.
-  Recall the help text.
-  Confirm the error message.

machine type:	Cirrus	Order
requir. impeller rev. speed cannot be maintained		drill calibr.
confirm with enter key or page to aid		machine
working menu	aid	Setup

Fig. 75

## 10.2 Failure of the forward speed sensor (Imp/100m)



With the failure of the forward speed sensor (Imp./100m), which is attached to the gearbox or with the electric drive option on the land wheel, operation can be continued after the input of a simulated forward speed.

The failure of the forward speed sensor is indicated by "seed drill lifted" on the display ("Drille angehoben").

In order to avoid possible sowing errors, exchange the defective sensor as soon as possible.

However, if a new sensor is not available in the short term, the sowing operation can continue as follows:

- Disconnect the signal cable of the defective forward speed sensor from the job computer.

- actuate  from the main menu.
-  enter a simulated forward speed.
- During operation the simulated speed must be maintained.



**As soon as impulses are sensed from the forward speed sensor the computer automatically changes over to the actual speed from the forward speed sensor.**

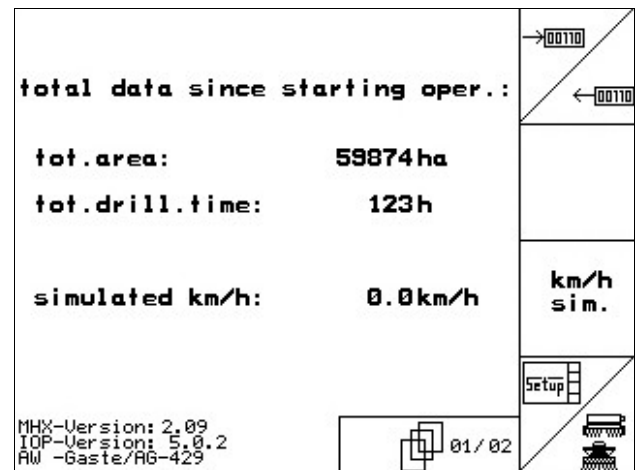


Fig. 76



# **AMAZONEN-WERKE**

H. DREYER GmbH & Co. KG

P. O. Box 51

D-49202 Hasbergen-Gaste  
Germany

Tel.: ++49 (0) 54 05 50 1-0  
Fax: ++49 (0) 54 05 50 11 93  
e-mail: [amazone@amazone.de](mailto:amazone@amazone.de)  
http:// [www.amazone.de](http://www.amazone.de)

---

Branch factories at: D-27794 Hude • D-04249 Leipzig • F-57602 Forbach  
Subsidiaries in England and France

Factories for: Mineral fertiliser broadcasters, field sprayers, seed drills, soil cultivation equipment  
multi purpose storage halls and groundcare municipal machinery

---